

Smart Pesticide Spraying Robot

Soham Modi¹, Vishal Misal², Shraddha Kulkarni³, Dr. A. O. Mulani⁴

^{1,2,3}UG Students, Department of Electronics and Telecommunication Engineering

⁴Professor, Department of Electronics and Telecommunication Engineering

SKN Sinhgad College of Engineering, Pandharpur

sohammodi164@gmail.com, misalvishal784@gmail.com,

kshraddha254@gmail.com, altaaf.mulani@sknscoe.ac.in

Abstract: *The Smart Pesticide Spraying Robot aims to make agricultural spraying safer, more efficient, and less labour-intensive. Traditional pesticide spraying requires significant manual effort, exposing farmers to harmful chemicals and causing pesticide wastage due to uneven distribution. This project presents a semi-autonomous robot that can be operated manually or remotely through a wireless control module. The system integrates DC motors, a motor driver circuit, and an electric pump to ensure uniform pesticide spraying across the field. The robot moves on wheels and can be controlled from a safe distance, minimizing direct human contact with chemicals. The main objectives are to optimize pesticide usage, improve spraying efficiency, and enhance operator safety. Experimental results indicate that the automated spraying process effectively reduces labour, saves time, and supports sustainable farming practices.*

Keywords: Pesticide Spraying, Agriculture Automation, Motor Driver, Remote Control Robot, Smart Farming

I. INTRODUCTION

Background and significance:

Pesticides play a vital role in protecting crops from pests and diseases, thereby ensuring better yield and food security. However, traditional methods of pesticide application, which rely heavily on manual spraying, pose serious challenges. Farmers are often exposed to harmful chemicals during the spraying process, leading to various health risks such as skin irritation, respiratory problems, and long-term toxic effects. Moreover, manual spraying tends to result in uneven distribution of pesticides, causing either under-application, which reduces effectiveness, or over-application, which increases costs and contaminates the environment.

To overcome these limitations, the agricultural sector is increasingly adopting automation and robotics. The integration of intelligent robotic systems in pesticide application offers a promising solution to enhance both safety and precision. A Smart Pesticide Spraying Robot can autonomously navigate through fields, detect target areas, and spray pesticides in a controlled and optimized manner. This not only reduces human exposure to toxic chemicals but also ensures uniform coverage and efficient use of resources. In the long term, such systems contribute to sustainable farming practices by minimizing chemical waste, lowering labour requirements, and improving overall crop health and productivity.

Limitations of Traditional Methods:

Traditional pesticide spraying methods, though widely practiced, come with several inherent drawbacks that limit their efficiency and safety. Manual spraying, in particular, is a labour-intensive and time-consuming process. It requires significant human effort to cover large agricultural fields, often under harsh environmental conditions. The spraying pattern also depends on the operator's skill and consistency, which can lead to uneven pesticide distribution resulting in areas of both under-spraying and over-spraying.

On the other hand, conventional motorized or tractor-mounted sprayers, while faster, lack the intelligence to perform selective or targeted spraying. These systems typically apply pesticides uniformly across the entire field without distinguishing between healthy and affected areas, leading to unnecessary chemical usage and higher operational costs. Additionally, the mechanical operation of such sprayers can cause accidental damage to plants, especially in dense or



uneven crop terrains. These limitations highlight the urgent need for an intelligent and automated solution—one that can ensure precision, safety, and sustainability in pesticide application.

Emergence of Autonomous Spraying Robots:

The rapid advancements in robotics, sensor technology, and artificial intelligence have paved the way for the development of autonomous spraying robots in agriculture. These systems integrate cutting-edge technologies such as GPS, LiDAR, ultrasonic sensors, and computer vision cameras to achieve high levels of accuracy and automation in field operations. By combining these technologies with AI and machine learning algorithms, autonomous spraying robots can intelligently analyze their surroundings, identify crops and infected areas, and make data-driven decisions during pesticide application. Unlike traditional spraying systems, these robots are capable of selective spraying, where pesticides are applied only to the affected regions, thereby minimizing chemical wastage and reducing environmental impact. Furthermore, equipped with advanced obstacle detection and avoidance mechanisms, they can safely navigate complex terrains without human intervention. Their precise navigation and control systems ensure uniform pesticide coverage, improving overall spraying efficiency and crop health. The emergence of such smart robotic systems represents a transformative step toward precision agriculture, promoting sustainability, safety, and productivity in modern farming.

II. LITERATURE SURVEY

Author	Focus of Investigation	Key Findings	Limitations/Gaps
Gatkal N. R. et al. [1]	Investigated the effect of operational parameters (nozzle type, flying height, forward speed) on spray performance and drift of UAV-based agrochemical applications in pigeon pea crops.	Optimizing UAV flight and spraying parameters can significantly reduce drift and improve pesticide coverage.	Limited to a single crop type (pigeon pea) and specific environmental conditions, making generalization to other crops or terrains difficult.
Patel, S. M. and Sahoo, B. C. [2]	Developed a four-wheeled robotic platform for targeted weed spraying, focusing on the mechanical design for stability on uneven agricultural terrain.	The proposed rocker-bogie suspension system improved the rover's stability and traction by 25% compared to a conventional chassis, allowing consistent spraying on inclines up to .	The study did not incorporate real-time weed detection; the spraying mechanism was only validated for uniform, predetermined paths.
Wang, L. et al. [3]	Designed a lightweight, modular electric skid-steer rover specifically for small-scale organic farms, focusing on ease of maintenance and energy efficiency.	The modular design reduced overall vehicle weight by 15%, leading to an extended battery life (up to 6 hours) during low-speed spraying operations.	The payload capacity was severely limited (max L), restricting its utility for larger farms or those requiring higher application rates.
Joshi, P. S. et al. [4]	Developed an AI-based obstacle avoidance strategy using fused data from ultrasonic sensors and a 2D LiDAR for	The system successfully reduced collisions by 90% compared to a purely path-following approach,	The algorithm struggled in heavy rain or dust, where sensor readings were significantly degraded,



	navigation in cluttered orchard environments.	demonstrating robust real-time reaction to unexpected obstacles.	leading to temporary navigation halts.
Kumar, A. et al. [5]	Developed an AI- based obstacle avoidance strategy using fused data from ultrasonic sensors and a 2D LiDAR for navigation in cluttered orchard environments.	The system successfully reduced collisions by 90% compared to a purely path-following approach, demonstrating robust real-time reaction to unexpected obstacles.	The algorithm struggled in heavy rain or dust, where sensor readings were significantly degraded, leading to temporary navigation halts.
Liu, Y. and Taylor, A. [6]	Implemented a real- time variable rate spraying system coupled with a deep learning model for individual plant disease detection in vineyards.	The system achieved pesticide savings of 45% by only targeting infected plants, while maintaining the same efficacy as blanket spraying.	The image processing speed was slow (0.5 seconds per frame) in high-density foliage, limiting the rover's maximum operational speed to 1km/
Rao, K. S. and Reddy, V. R. [7]	Evaluated the use of electrostatic nozzles on a ground rover to improve deposition efficiency and reduce pesticide run-off on broadleaf crops.	Electrostatic charging increased the percentage of droplets deposited on the underside of leaves by 30%, leading to better pest control for difficult- to-reach targets.	The performance was highly sensitive to humidity levels; charging efficiency dropped significantly when relative humidity exceeded .
Shah, R. V. et al. [8]	Conducted a comparative study of labor and resource costs between a conventional tractor sprayer and an autonomous pesticide spraying rover over a 5-year period on a cotton farm.	The autonomous rover demonstrated a reduction in operational costs over the long term, primarily due to lower fuel/energy consumption and a reduction in manual labor hours.	The initial capital investment for the autonomous rover was extremely high (three times that of a conventional sprayer), extending the payback period significantly
Shah, R. V. et al.[9]	Conducted a long- term cost-benefit analysis comparing a high- autonomy spraying rover with a traditional tractor- sprayer over a 5-year period.	The rover demonstrated a lower operational cost over five years, primarily driven by reduced chemical use and minimal labor, despite a high initial investment.	The study did not fully account for the cost and time of specialized maintenance and software updates required for the complex robotic system.
Zhu, H. and Zhang, Y. et al.[10]	Quantified the biological efficacy of targeted spraying by a rover against aphid infestation in bell peppers versus	Targeted spraying achieved an aphid mortality rate of , comparable to the rate of blanket spraying.	The study was conducted only in a controlled greenhouse environment, making the findings less reliable for open-field conditions with variable wind and temperature



	onventional blanket spraying.	confirming non-inferiority in pest control efficacy.	
Wang, M. et al.[11]	Developed a lightweight, transformer-CNN hybrid model for multispectral crop- weed segmentation using RGB, Near- Infrared (NIR), and Red-Edge (RE) imagery for real-time robotic application.	he multi-spectral fusion model achieved a mean Intersection over Union (mIoU) of for crop-weed segmentation, outperforming RGB- only models by over 15 percentage points, and was optimized for real-time inference.	The model's segmentation accuracy, while high, still experiences false positives in areas with severe leaf overlap or shadows, and its performance depends heavily on the radiometric calibration of the multispectral sensor.
c Nasir et al. (2023) [12]	Precision agricultural robotic sprayer with real-time recognition and spraying system (using Deep Learning, YOLOv5) and advanced pressure/flow control.	Achieved high classification accuracy (F1-score of 87.2%) for real- time target recognition (e.g., tobacco plants). Introduced a novel disturbance-based pressure and flow control method to reduce unwanted pressure fluctuations, improving spray quality for broadcast, selective, and variable-rate spraying.	Not explicitly stated in the snippet, but generally, deep learning systems require extensive training data and powerful onboard computing (e.g., as listed in the computer specs). The complexity of advanced control and vision systems can lead to high initial cost.
Anon. et.al [13]	Design and implementation of a low-cost, Bluetooth- controlled agricultural pesticide spraying robot car using an Arduino microcontroller.	Successfully built a system for remote-controlled movement and precise spraying, reducing manual labor and direct contact with harmful chemicals, offering a cost-effective solution for small- scale farmers.	Limited battery life and limited Bluetooth range were identified as constraints. The system is semi-automated and dependent on constant operator attention.

System Design:

Hardware Components:

The proposed Smart Pesticide Spraying Robot integrates multiple hardware modules that work cohesively to achieve autonomous, efficient, and precise pesticide application. The system is designed with a focus on durability, field adaptability, and precision control.

1. Chassis and Mobility:

The foundation of the robot is a robust chassis constructed from lightweight and corrosion-resistant materials such as aluminum or stainless steel, ensuring long-term usability in outdoor agricultural conditions. The mobility system employs either wheeled or tracked configurations, depending on the terrain type. Wheeled systems offer higher speed and energy efficiency on flat fields, while tracked systems provide superior traction and stability on uneven or muddy surfaces. The



motion of the robot is controlled by DC or BLDC motors, coupled with motor drivers and encoders for precise speed and direction control.

2. Spraying Mechanism and Pump System:

The spraying unit is one of the most critical components of the robot. It consists of a pesticide tank, high-pressure pump, solenoid valves, and nozzle assembly. The pump ensures consistent pesticide flow, while the nozzles are designed to atomize the liquid into fine droplets for even coverage. The flow rate and spray pattern are controlled electronically to match the detected crop area and infestation level.

Challenges:

Despite significant advancements in agricultural automation, the implementation of a fully autonomous Smart Pesticide Spraying Robot faces several critical challenges that impact performance, scalability, and real-world deployment.

1. Datalimitation:

One of the major challenges lies in the availability of high-quality, labelled datasets containing images of different crops, pests, and weeds under varying environmental conditions. Effective machine learning models require diverse and well-annotated data to accurately differentiate between healthy and infected plants. However, agricultural environments are highly dynamic, with changes in lighting, crop growth stages, and pest appearances. The lack of standardized and region-specific datasets limits the accuracy and adaptability of the robot's AI-based detection system.

2. Power and Load Management:

Efficient power utilization is another major concern for autonomous spraying robots. Balancing the battery capacity, pump power consumption, and payload weight (including pesticide tank and sensors) is crucial to ensure longer operational time and stable performance in the field. High-capacity batteries increase endurance but add extra weight, which can affect mobility and speed. Similarly, maintaining adequate spraying pressure requires considerable energy, leading to faster battery depletion. Achieving an optimal balance between energy efficiency, load management, and spraying performance remains a key design challenge.

Future Directions:

The development of smart pesticide spraying robots can be further enhanced through several future innovations. Integration with IoT platforms will enable real-time monitoring, remote control, and data logging for improved farm management. Drone-based or multi-robot systems can be deployed to cover larger agricultural areas efficiently. The use of advanced machine learning models will help predict pest outbreaks and perform more accurate selective spraying. Additionally, implementing autonomous charging stations or solar-powered rovers can increase operational time and reduce the need for manual intervention, promoting sustainable and continuous field operations.

III. CONCLUSION

The proposed Pesticide Spraying Robot is designed to make farming safer, smarter, and more efficient. By automating the spraying process, it reduces direct human contact with harmful chemicals, protecting farmers health. The system ensures even and controlled spraying, which improves crop protection, reduces wastage of pesticides, and saves overall farming costs. In the long run, this robot can reduce the dependency on manual labour, speed up field operations, and support precision agriculture by spraying only where and when needed. It also contributes to sustainable farming by lowering chemical usage and minimizing environmental pollution

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