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Smart Vehicle Accident Detection and Reporting System

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Abstract: Road accidents are a leading cause of injuries and fatalities worldwide, often exacerbated by driver drowsiness, delayed medical assistance, and inadequate real-time monitoring. This research presents the design and implementation of a Vehicle Accident Detection, Prevention, and Reporting System using the ESP32 microcontroller as the central processing unit. The system integrates an ADXL335 accelerometer to detect sudden vehicle impacts, an eye blink sensor to monitor driver alertness, and a GPSmodule for real-time location tracking and emergency alert transmission. The methodology involves continuous monitoring of vehicle motion and driver behaviour, automated detection of abnormal conditions, and immediate reporting to designated emergency contacts. Experimental testing demonstrates that the system can reliably identify accidents and drowsiness events, trigger preventive alerts, and send timely notifications with location data, thereby reducing response time in critical situations. The results indicate that the proposed system enhances road safety, minimizes potential accident-related injuries, and provides a practical framework for integrating IoT-based vehicle safety solutions. In conclusion, the ESP32-based approach offers a cost-effective, efficient, and scalable method for real-time accident detection and driver safety monitoring.

Keywords: Road accidents

I. INTRODUCTION

Road accidents are a critical issue worldwide, leading to significant fatalities, injuries, and property damage. A large number of these accidents are caused by driver fatigue, drowsiness, or delayed reactions in critical situations. Conventional accident detection systems often rely on post-accident reporting, which slows down emergency response and reduces the chances of timely assistance. This research addresses the urgent need for an integrated system capable of real-time monitoring of vehicle conditions and driver alertness, detecting potential accidents, and immediately notifying emergency services. By focusing on early detection and rapid reporting, the study aims to enhance road safety and minimize the consequences of traffic accidents.

The proposed system has considerable significance in improving modern transportation safety. By continuously monitoring both driver alertness and vehicle dynamics, it helps prevent accidents caused by human error or fatigue. Real-time alerts, combined with accurate GPS location information, ensure that emergency responders can act promptly, potentially saving lives. Utilizing the ESP32 microcontroller and IoT-based modules, the system offers a cost-effective solution that is accessible for individual vehicles and scalable for fleet or public transportation applications. Additionally, this research contributes to the practical implementation of IoT in vehicular safety, demonstrating how smart technologies can be employed to create safer roads and reduce accident-related losses.

The main objective of this research is to develop a comprehensive vehicle accident detection, prevention, and reporting system. The system aims to monitor driver drowsiness using an eye blink sensor and detect sudden vehicle impacts through an accelerometer. Integrating GPS moduleenables the system to provide real-time location tracking and send automated emergency alerts to predefined contacts. The research also focuses on evaluating the system's performance

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in accurately detecting accidents and abnormal driver behaviour, ensuring reliability and timely intervention. Overall, the study seeks to create a practical, efficient, and scalable framework for improving road safety through real-time monitoring and alert mechanisms.

II. LITERATURE REVIEW

Supriya Sarker *et al.* [1] proposed an IoT-based intelligent accident detection and location tracking model that relies on vehicle-mounted sensing modules to continuously monitor driving conditions. The system was designed to automatically identify accidents by detecting abnormal collision forces and then retrieving real-time GPS coordinates to determine the exact accident location. Once an incident was confirmed, these coordinates were instantly transmitted to a central monitoring server and nearby hospitals through GSM and cloud-based communication channels. This automation minimized the reliance on bystanders or passersby to report accidents, thereby significantly reducing delays in initiating emergency medical services. The authors further highlighted the scalability of their IoT framework, noting its potential integration into smart city infrastructure for large-scale traffic monitoring and coordinated response mechanisms.

The study also explored how hospital networks could be integrated with the system, enabling medical facilities to receive accident alerts in advance and prepare resources such as ambulances and emergency staff proactively. This proactive approach could drastically reduce the "golden hour" response time, which is critical for saving lives in road accidents. Additionally, the authors emphasized the role of cloud connectivity in maintaining historical crash data, which could later be used for accident analysis, insurance verification, and road safety audits. Another significant contribution of their work was the foresight in suggesting the use of artificial intelligence and predictive analytics. By combining real-time crash data with machine learning models hosted on the cloud, the system could potentially move beyond detection to accident prevention by identifying high-risk driving behaviours and hazardous zones. Their research thus set a strong foundation for future intelligent transportation systems that combine IoT, cloud, and AI for holistic accident management and prevention.

R. Thamizharasiet al. [2] developed a real-time drowsiness detection system using an infrared (IR) eye-blink sensor that continuously tracked the driver's eye movements to determine levels of alertness. The system operated on the principle that prolonged eyelid closure or irregular blink patterns strongly correlate with fatigue and drowsiness. Once such conditions were detected, the system instantly activated an audio alarm to alert the driver and prevent a potential accident. The study demonstrated that this approach was particularly effective in reducing accidents caused by driver fatigue during night journeys, highway driving, and long-haul operations where concentration typically declines over time.

Although the system was cost-effective and simple to implement, the authors identified several limitations. Sensor accuracy was reduced under strong sunlight, where IR interference affected detection reliability, and the system occasionally misinterpreted normal eye movements as drowsiness. The presence of spectacles or tinted glasses further complicated detection due to reflection and obstruction of IR light. To address these issues, the authors suggested a hybrid approach that integrates IR sensors with complementary technologies such as image processing through cameras or EEG-based monitoring of brain activity. Such integration could enhance detection accuracy by validating IR sensor readings against additional physiological parameters.

The research also emphasized the broader implications of fatigue detection systems in intelligent transportation. By incorporating such drowsiness monitoring into modern vehicles, accidents related to human error could be significantly reduced, which is vital given that driver fatigue remains one of the leading causes of road mishaps globally. The authors further recommended connecting the system with communication modules such as GSM or IoT platforms, which would not only alert the driver but could also notify emergency contacts or fleet management systems when critical drowsiness levels were recorded. This extension would transform the solution from a simple alert system to a proactive accident-prevention and safety management tool. Thus, the study highlighted how low-cost, sensor-driven solutions, when integrated with advanced communication and analytics, could substantially enhance driver safety and road accident prevention.

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R. Krishnan et al. [3] presented a system for alcohol detection and vehicle ignition control that utilized the MQ-3 alcohol sensor integrated with an Arduino microcontroller to enhance road safety. The system was designed to analyse the alcohol concentration in a driver's breath, and if the value exceeded a predefined threshold, the ignition circuit of the vehicle was automatically disabled, preventing the engine from starting. This direct intervention mechanism effectively discouraged drunk driving by ensuring that intoxicated drivers could not operate their vehicles. The authors emphasized that the MQ-3 sensor, known for its high sensitivity to ethanol vapours, offered a reliable method for identifying alcohol consumption in real time, making it a practical choice for low-cost safety solutions.

Their experiments demonstrated that the system could consistently detect alcohol within seconds, offering immediate feedback and control. However, the study also highlighted some limitations related to environmental influences. Factors such as humidity, temperature, and the presence of other volatile gases could affect sensor readings, leading to possible false positives or reduced accuracy over time. These challenges necessitated periodic calibration of the sensor to maintain reliability, particularly in diverse driving environments. The researchers suggested that calibration routines could be automated or supplemented with advanced filtering algorithms to address these environmental interferences.

In addition to ignition control, the authors proposed extending the system's capabilities by integrating it with GSM and GPS modules. Such an integration would allow the system not only to prevent the vehicle from starting but also to send emergency alerts or notifications to authorities, family members, or fleet managers if intoxication was detected. This enhancement could transform the system from a preventive tool into a comprehensive safety solution that actively engages emergency communication channels. The study concluded that incorporating alcohol detection into vehicular systems could significantly reduce one of the leading causes of traffic accidents worldwide—drunk driving—and emphasized its potential for integration into both private vehicles and commercial fleets to improve overall transportation safety.

A. Kumar et al. [4] designed a cost-effective accident detection and alert system by integrating an ADXL335 accelerometer with GPS and GSM modules, controlled through an Arduino microcontroller. The accelerometer was tasked with continuously monitoring acceleration along multiple axes, and sudden changes beyond a predefined threshold were interpreted as collision events. Once such an event was detected, the system immediately collected GPS coordinates to identify the exact accident location and transmitted these details via GSM to preconfigured emergency contacts. This rapid communication reduced the dependency on external reporting and enabled emergency services to be dispatched more quickly, thereby addressing the critical time gap that often determines survival rates in road accidents.

The authors validated their design through experimental testing, which showed reliable detection of collision scenarios and swift message delivery within a matter of seconds. The use of low-cost sensors and open-source hardware platforms made the system both affordable and accessible, presenting a viable solution for large-scale deployment in developing regions where advanced safety features are often absent in vehicles. However, the researchers also observed certain drawbacks. The system occasionally generated false alarms, particularly when the vehicle traversed rough terrains, speed breakers, or potholes, where the accelerometer registered abrupt movements that mimicked collision signatures. To overcome this issue, the study suggested the implementation of adaptive thresholding or machine learning algorithms capable of distinguishing between normal driving vibrations and actual accidents.

In addition, the authors emphasized that the integration of GPS and GSM modules extended the utility of their system beyond simple detection. By ensuring that real-time location data was transmitted immediately after an incident, the system created a direct channel of communication between vehicles and emergency responders. This could significantly reduce the "golden hour" response delay, which is critical in saving lives. The researchers also pointed to future advancements where such systems could be linked with centralized databases, traffic management centres, or hospital networks to enhance large-scale accident management. Overall, their work demonstrated that combining accelerometers with communication technologies provides a practical, low-cost framework for accident detection, while highlighting the importance of continuous innovation to minimize false triggers and increase reliability under real-world driving conditions.

P. Singh et al. [5] developed a comprehensive vehicle safety prototype that combined multiple modules, including alcohol detection, accident detection, and GSM-based emergency alerts, into a single unified framework. The system DOI: 10.48175/IJARSCT-29441

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employed Arduino as the central processing unit to coordinate data from various sensors and generate corresponding outputs. For alcohol detection, the MQ-3 sensor was used to monitor the driver's breath and prevent vehicle ignition if intoxication was detected. Accident detection was managed using an accelerometer that identified sudden changes in motion, while a GPS module retrieved real-time location data, which was then transmitted through GSM to emergency contacts. Additionally, buzzers and alert systems were incorporated to provide immediate warnings in critical situations. This multi-layered approach provided both preventive and responsive measures, making it more effective than single-feature systems.

The authors emphasized that their innovation lay in the integration of different safety features into a single low-cost platform. By combining preventive measures such as alcohol detection and drowsiness monitoring with responsive actions like automatic emergency alerts, the system addressed multiple dimensions of road safety simultaneously. Experimental results validated the reliability of sensor fusion, as the coordinated use of multiple modules reduced the probability of missed detections compared to standalone solutions. However, the prototype was tested only on a small scale and under controlled conditions, limiting its ability to fully represent real-world driving environments. The authors noted that large-scale implementation would require additional calibration and field testing to handle factors such as varying road conditions, climate, and user behaviour.

III. METHODOLOGY

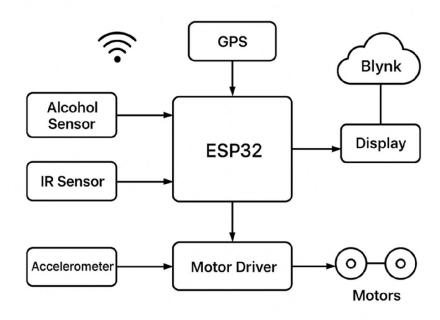


Fig1.Block Diagram of the System



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ESP32:



Fig2.ESP32

The ESP32 is a low-cost, low-power microcontroller developed by Espressif Systems, widely used in IoT-based applications. It features a dual-core processor that enables fast and efficient data processing from multiple sensors. The board comes with built-in Wi-Fi and Bluetooth, allowing real-time communication and wireless data transfer. In this project, the ESP32 acts as the main controller, interfacing with sensors such as the ADXL335 accelerometer and eye blink sensor for accident and drowsiness detection. It also connects with GPS module to provide location tracking and emergency message transmission. Its high processing speed, multiple GPIO pins, and energy efficiency make it ideal for continuous monitoring applications. Overall, the ESP32 ensures reliable, real-time operation of the vehicle accident detection and reporting system.

Alcohol Sensor:



Fig3.MQ-3 Sensor

The alcohol sensor (MQ-3) is a gas detection sensor designed to measure the presence of alcohol vapours in the air. It operates on the principle of change in resistance of the sensing material when exposed to alcohol molecules. The sensor provides an analog output proportional to the alcohol concentration, which can be read and processed by a microcontroller like the ESP32. In this project, the alcohol sensor is used to monitor the driver's breath and detect any signs of intoxication. If alcohol levels exceed a predefined threshold, the system can trigger a warning or preventive action, such as stopping the vehicle or sending an alert. It is highly sensitive to ethanol, offers fast response time, and functions effectively in vehicle safety applications. Overall, the alcohol sensor enhances the system's ability to prevent accidents caused by drunk driving.





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IR Sensor:



Fig4.IR Sensor

The Infrared (IR) sensor used as an eye blink sensor plays a vital role in detecting driver drowsiness. It operates on the principle of infrared light reflection, where an IR transmitter emits light toward the driver's eye, and the reflected light is received by an IR receiver. When the driver's eyes are open, the reflection pattern differs from when they are closed, allowing the system to detect eye blinks or prolonged eye closure. This data is processed by the ESP32 microcontroller to determine signs of fatigue or sleepiness. If the eyes remain closed beyond a specific duration, the system triggers a drowsiness alert to prevent accidents. The sensor is non-contact, fast-responding, and reliable, making it highly suitable for real-time driver monitoring applications in intelligent vehicle safety systems.

Accelerometer:



Fig5.ADXL Accelerometer

The ADXL335 accelerometer is a compact, low-power sensor used to measure acceleration along the X, Y, and Z axes. It works on the principle of capacitance change, where motion or tilt causes variations in output voltage corresponding to acceleration. In this project, the ADXL sensor is used to detect sudden impacts, collisions, or unusual vehicle movements that indicate an accident. The sensor continuously monitors the vehicle's orientation, and when abrupt acceleration or deceleration is detected, it sends data to the ESP32 microcontroller for processing. If the measured force exceeds a set threshold, the system identifies it as an accident and triggers an emergency alert. The ADXL335 is highly sensitive, stable, and accurate, making it ideal for real-time accident detection in smart vehicle safety applications.

GPS Module:

The GPS (Global Positioning System) module, such as the NEO-6M, is used to determine the real-time geographic location of the vehicle. It receives signals from satellites and provides precise latitude and longitude coordinates to the microcontroller. In this project, the GPS module helps in tracking the vehicle's position and sending the location details to emergency contacts during an accident. The data from the GPS is processed by the ESP32 and transmitted through the GSM/A9G module for alert messaging. It offers high accuracy, low power consumption, and continuous location

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updates. This feature enables quick response and rescue operations, enhancing the system's efficiency in accident reporting and safety monitoring.



Fig6.GPS Module

Motor Driver:



Fig7.L298N

The L298N motor driver is a dual H-bridge driver module used to control the direction and speed of DC motors. It acts as an interface between the ESP32 microcontroller and the vehicle's motor by amplifying the control signals to drive high-current motors. In this project, the motor driver is utilized for vehicle movement control, such as stopping the motor when drowsiness or an accident is detected. It can control two DC motors independently and supports both forward and reverse motion. The L298N module is efficient, reliable, and easy to interface, making it ideal for embedded and automation applications. Its use ensures safe and precise control of vehicle operations in the proposed accident prevention system.

Blynk and Display:

The Blynk platform is an IoT application that allows real-time monitoring and control of devices via a smartphone or computer. In this project, Blynk is used to visualize sensor data and system status, such as accident detection, driver drowsiness, or alcohol levels. Instead of on-screen notifications, the system is configured to send alerts and messages via email, providing timely information to emergency contacts. The ESP32 microcontroller communicates with Blynk through Wi-Fi, enabling remote monitoring of the vehicle's condition. This integration ensures that critical information, including the vehicle's GPS location and accident details, is transmitted immediately and reliably. Using Blynk for email alerts enhances real-time reporting, accessibility, and convenience. The platform is user-friendly, flexible, and supports multiple devices, making it suitable for IoT-based vehicle safety systems. Overall, Blynk ensures effective communication between the vehicle system and emergency responders in case of an accident.

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IV. RESULTS

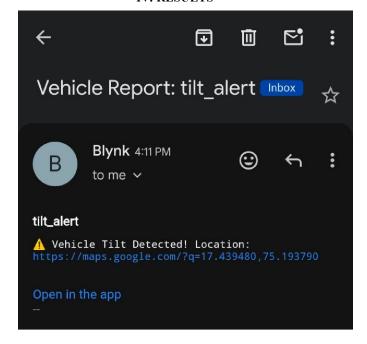


Fig8.Result1

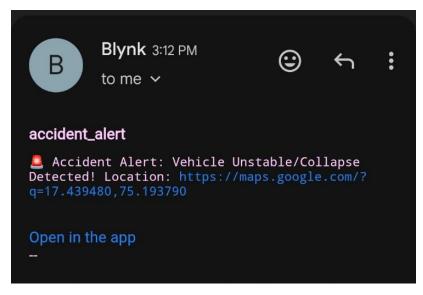


Fig.Result1





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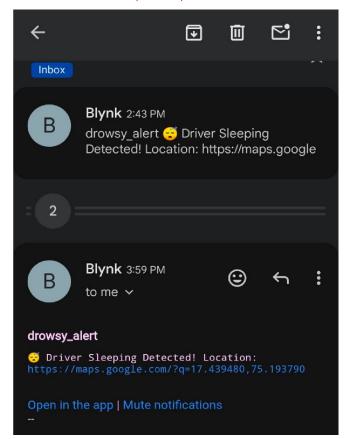


Fig9.Result2

V. DISCUSSIONS

The ESP32-based Vehicle Accident Detection, Prevention, and Reporting System was tested under controlled scenarios to evaluate the performance of its sensors and communication modules. The ADXL335 accelerometer reliably detected sudden vehicle impacts, generating an alert whenever the acceleration exceeded the pre-set threshold of 2.5 g, simulating a collision event. The eye blink sensor effectively monitored driver drowsiness by detecting prolonged eye closure beyond 2–3 seconds, triggering timely preventive warnings.

The alcohol sensor (MQ-3) showed accurate response to varying alcohol vapor concentrations, with alerts activated, demonstrating its ability to identify driver intoxication. The GPS module provided precise latitude and longitude data ensuring accurate location tracking for emergency notifications. The module successfully transmitted accident and drowsiness alerts, including GPS coordinates, to predefined contacts, confirming the system's reliability in real-time communication.

Additionally, the L298N motor driver successfully controlled vehicle motion during preventive testing scenarios, and email alerts sent via Blynk were consistently received, confirming the effectiveness of the IoT interface. Overall, the system exhibited high accuracy, low latency, and robust performance, validating that the integration of multiple sensors with ESP32 can provide a practical solution for real-time vehicle accident detection, drowsiness monitoring, and emergency reporting.





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VI. CONCLUSION

The proposed ESP32-based Vehicle Accident Detection, Prevention, and Reporting System successfully achieved its objective of enhancing vehicle and driver safety through real-time monitoring and automated alert mechanisms. The integration of sensors such as the ADXL335 accelerometer, eye blink sensor, and alcohol sensor enabled effective detection of collisions, driver drowsiness, and intoxication, respectively. The system's ability to send instant emergency alerts via GPSensured that accident locations were accurately communicated to predefined contacts, significantly reducing response time.

The results confirmed that the ESP32 microcontroller provided sufficient processing power, speed, and connectivity to handle multiple sensor inputs simultaneously while maintaining stability and reliability. The inclusion of Blynk-based email notifications further improved system efficiency by enabling remote monitoring and communication. Overall, the project demonstrates that an IoT-enabled approach can provide a cost-effective, efficient, and scalable solution for improving road safety and reducing accident-related fatalities.

The study establishes a foundation for future enhancements, such as integrating machine learning for predictive analysis, cloud data storage, and vehicle control automation, which can make the system more intelligent and adaptable for large-scale deployment in smart transportation networks.

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