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Object Detection Radar with Arduino Uno

¹Prathamesh Karande, ²Shivam Pandhare, ³Soham Gavhane , ⁴Amol Hake, ⁵Prof. M. M. Zade ^{1,2,3,4}UG Students, Department of Electronics and Telecommunication Engineering ⁵Assistant Professor, Department of Electronics and Telecommunication Engineering SKN Sinhgad College of Engineering, Pandharpur karandeprathamesh244@gmail.com, shivampandhare0285@gmail.com,

sohamgavhane07@gmail.com, ahake2123@gmail.com,

Abstract: The advancement of embedded systems and sensor technology has enabled the development of low-cost radar systems for object detection and distance measurement. This project, "Object Detection Radar with Arduino Uno," presents a compact and efficient system designed to detect objects within a defined range using ultrasonic sensing technology. The system is built around the Arduino Uno microcontroller, which processes distance data obtained from the HC-SR04 ultrasonic sensor and visually represents the detected object on a servo-mounted radar interface. The rotating servo motor enables the sensor to scan a 180-degree field, while the Arduino calculates the distance based on the time delay of the ultrasonic pulse reflection. The detected objects are graphically displayed on a computer screen using Processing IDE, simulating a real radar system. This project demonstrates how radar principles can be implemented using affordable electronic components, making it a valuable educational and practical tool for understanding distance measurement, obstacle detection, and embedded system integration. The proposed system has potential applications in robotics, vehicle collision avoidance, security systems, and automation. Overall, the design highlights the effectiveness of combining ultrasonic sensing with microcontroller programming to achieve real-time object detection and visualization..

Keywords: embedded systems

I. INTRODUCTION

In today's world, automation and sensing technologies play a crucial role in enhancing safety, efficiency, and intelligence across various systems. Object detection is one of the fundamental aspects of modern automation, with applications ranging from autonomous vehicles and robotics to security surveillance and industrial automation. Radar systems, which operate on the principle of detecting reflected signals from objects, have been widely used for decades in aviation, defense, and navigation. However, traditional radar systems are often complex and expensive, limiting their accessibility for small-scale or educational purposes.

The Object Detection Radar with Arduino Uno project aims to create a cost-effective and easy-to-understand radar prototype that can detect and display the position of nearby objects in real time. The system employs an HC-SR04 ultrasonic sensor to measure distance by transmitting and receiving sound waves. The Arduino Uno microcontroller serves as the core processing unit, calculating the distance based on the time delay between the transmitted and reflected signals. A servo motor is used to rotate the sensor across a specific angular range, enabling the system to scan the surrounding area. The detected objects are then visualized on a **Processing IDE interface**, simulating a real radar display.

This project not only demonstrates the principles of radar operation but also provides hands-on experience in embedded system design, sensor integration, and data visualization. It highlights how affordable components can be used to develop functional prototypes for real-world applications such as collision avoidance systems, robotic navigation, and obstacle detection. By combining hardware and software technologies, the project bridges the gap between theoretical radar concepts and practical implementation.

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II. LITERATURE SURVEY

Table 1: Object Detection Radar with Arduino Uno

Paper /	System	Cost	Ease of	Performance	User	Limitations
Project	Architecture		Implementation		Experience	
Khan et al.	Ultrasonic-	Low (<\$30)	Easy setup	Accurate in	Simple	Limited
	based obstacle			short range	distance	detection
	detection using				display	angle.
	Arduino					
Rahman et	Radar prototype	Low (<\$35)	Moderate	Real-time	Interactive	Servo Delay
al.	using Arduino			visualization	radar interface	Affects
	and Processing					precision.
Sharma et	IoT-based	Moderate	Moderate	Remote	Mobile-based	Requires Wi-
al.	obstacle	(<\$50)		monitoring	alerts	Fi
	detection using					connectivity.
	NodeMCU					
Joshi et al	Smart vehicle	Moderate	Complex	High accuracy	Improved	High
	collision				road safety	processing
	avoidance using					demand
	sensors					
Mehta &	Ultrasonic radar	High	Moderate	Fast image	GUI-based	Costly
Singh	using	(>□4000)		processing	visualization	hardware.
	Raspberry Pi					
	High					

III. PROPOSED METHODOLOGY

The proposed Object Detection Radar System is designed using Arduino Uno as the core processing unit, interfaced with a HC-SR04 ultrasonic sensor, SG90 servo motor, and computer or Android device for radar visualization.

Object Detection Radar System

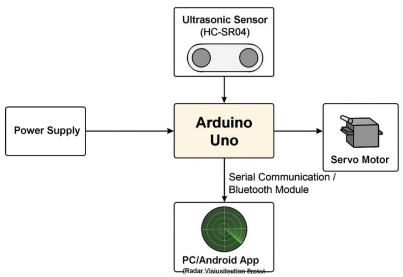


Figure 1: Block Diagram of Proposed System









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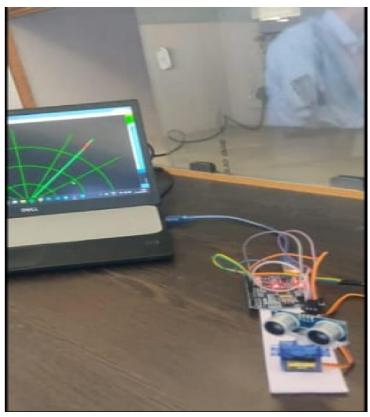
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IV. CONCLUSION

The Object Detection Radar using Arduino Uno successfully demonstrates a simple yet effective method of real-time object detection and visualization. The system efficiently measures the distance of nearby objects and presents them on a radar-style display, providing valuable insights into spatial awareness. By combining low-cost hardware with simple software logic, this project serves as an ideal prototype for educational, research, and security applications.

Future developments may include integrating IoT for cloud monitoring, AI-based object classification, or GPS integration for autonomous navigation systems. Thus, this system highlights how affordable embedded technology can replicate complex radar systems for practical and scalable solutions.

V. RESULT



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- 220.Mr. Mahesh M Zade, "Performance analysis of PSNR Vs. Impulse Noise for the enhancement of Image using SMF", Journal of Applied Science & Computations (JASC UGC Approved), Volume VI, Issue II, Feb.2019
- **221.**Mr. Mahesh M Zade, "Classification of Power Quality Disturbances Using SVM & their Efficiency Comparison", Journal of Applied Science & Computations (JASC UGC Approved), Volume VI, Issue II, Feb.2019
- 222.Mr. Mahesh M Zade, "Dynamic Clustering of Wireless Sensor Network Using Modified AODV", Journal of Applied Science & Computations (JASC UGC Approved), Volume VI, Issue II, Feb.2019
- **223.**Mr. Mahesh M Zade, "Performance analysis of PSNR Vs. Impulse Noise for the enhancement of Image using SMF", National Conference on Mathematical Modeling and Computational Intelligence 2K19 (MMCI-2k19), in association with JASC, at S. B. Patil College of Engineering, Indapur, Feb.2019
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- **226.**Mr. Mahesh M Zade & Mr.S.M.Karve,"Performance Analysis of Median Filter for Enhancement of Highly Corrupted Images", National Conference on Advanced Trends in Engineering, Association with IRJMS, Karmyogi Engineering College, Shelave, Pandharpur, March 2016.
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