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Brainy Line Following Robot with Obstacle Detection

Fundipalle Bhagyshri Rajshekhar[1], Babar Sakshi Kailash[2], Koshti Nikita Bibishan[3], Shaikh.Heena. T.[4]

[1,2,3] UG Students, Department Electronics and Telecommunication

[4]Assistant Professor, Department Electronics and Telecommunication

Brahmdevdada Mane Institute of Technology, Solapur, Maharashtra, India

bhgyshrifundipalle@gmail.com

Abstract: *Autonomous mobile robots play a vital role in modern automation systems. This paper presents the design and implementation of an autonomous line-following robot integrated with obstacle detection. The robot uses infrared (IR) sensors for line tracking and an ultrasonic sensor for obstacle detection. When an obstacle is detected, the robot halts and re-routes if possible. The system is built using Arduino microcontroller technology and is aimed at applications in industries, logistics, and smart transportation. The integration of both line following and obstacle avoidance enhances the robot's real-time decision-making capabilities in dynamic environments. This project presents the design and implementation of a Greenline-following robot integrated with an obstacle detection system. The robot is programmed to autonomously navigate by following a green-colored path using color sensors, ensuring accurate tracking even along curved or complex routes. To enhance safety and adaptability, the system incorporates ultrasonic sensors that detect and respond to obstacles in the robot's path. When an obstruction is detected, the robot either pauses or reroutes to avoid collisions, depending on the programmed logic. This combination of line-following and real-time obstacle detection makes the robot suitable for various applications, including smart logistics, automated delivery, and educational robotics. The project emphasizes efficiency, reliability, and real-world applicability through a cost-effective and scalable design.*

Keywords: Autonomous Robot, Line Following, Obstacle Detection, IR Sensor, Ultrasonic Sensor, Arduino, Mobile Robotics

I. INTRODUCTION

Autonomous mobile robots have become increasingly essential in automation, where they reduce human labor and improve efficiency. Among various types, line-following robots are prominent in tasks such as warehouse item delivery and factory automation. However, conventional line followers lack dynamic environment awareness and may fail when obstacles block their path[1-20].

To address this limitation, this project implements a hybrid approach: a line-following robot equipped with an obstacle detection mechanism. The robot follows a predefined path using IR sensors and monitors for obstacles using an ultrasonic sensor. When an obstacle is detected, the robot stops and waits or re-routes depending on the configuration

Unlike traditional line-following robots that rely on black or white lines, this design uses a green line as its guiding path, offering a unique approach suited for specific operational environments. By integrating color sensors for path detection and ultrasonic sensors for obstacle avoidance, the robot can make real-time decisions to stop, reroute, or continue its path, depending on the surrounding conditions. The primary goal of this project is to build a reliable and intelligent robotic system that demonstrates autonomous movement, environmental awareness, and practical functionality. Through this project, we aim to explore the integration of sensor technologies, basic control systems, and real-world problem-solving using robotics

In the digital veins of a micro-controller, a silent sentry awakens. Its purpose: precision. Its path: a stark, defined line upon the floor. This isn't just any automaton; this is 'Artemis,' our Brainy Line Following Robot with Obstacle Detection, a testament to intelligent, autonomous navigation.

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At its core, Artemis is a master of the monochrome. A keen array of infrared sensors, like a multi-faceted eye, constantly scans the terrain beneath its chassis. They read the stark contrast between the guiding black line and the lighter surface, translating photons into binary commands. Its internal algorithms, a finely tuned dance of proportional-integral-derivative (PID) control, instruct its differential drive motors. A slight drift to the left? The right wheel speeds up, the left slows. A gentle curve ahead? Both wheels adjust, maintaining that seamless, almost balletic flow along the designated path. It's a focused, unwavering pursuit of linearity.

But the world isn't a pristine canvas. It's dynamic, unpredictable. This is where Artemis sheds its simple follower skin and reveals its true 'brainy' nature. Perched prominently, often an ultrasonic sensor or a pair of infrared distance sensors, acts as its forward-looking sentinel. These sensors emit sound waves or infrared light, listening for echoes or reflections, gauging the distance to anything that dares to intrude upon its world.

Imagine Artemis diligently tracing its path, a picture of focused determination. Suddenly, an unforeseen object – a misplaced box, a curious pet, a dropped tool – appears directly in its trajectory. The line sensors still scream 'forward!', but the obstacle detector shouts 'halt!'. This is the moment of intelligent arbitration[21-50].

Its tiny, silicon brain doesn't panic. Instead, pre-programmed algorithms, a complex web of 'if-then-else' statements, kick into high gear. It assesses: Is the obstacle temporary? Can it be circumnavigated with a slight deviation? Or does it demand a complete stop and signal for intervention? If the obstacle is within a critical threshold and the line is blocked, Artemis doesn't just crash. It stops, its motors falling silent, perhaps illuminating a warning LED or even emitting a gentle beep to alert human operators. If the path around the obstacle is clear, even for a moment, its brain calculates a temporary detour, a brief deviation from the sacred line, before gracefully re-acquiring its path beyond the impediment.

This fusion of capabilities is what truly defines its "brainy" moniker. It's not just reactive; it's proactive in its safety. It prioritizes the integrity of its mission while safeguarding its surroundings and itself. Underneath its streamlined shell lies an embedded microcontroller – perhaps an Arduino, an ESP32, or a Raspberry Pi Zero – the central nervous system translating sensor inputs into precise motor commands. It balances speed with safety, efficiency with awareness.

Such a robot isn't a mere toy. Envision it in a warehouse, ferrying components along designated paths, autonomously stopping if a human steps into its zone, preventing collisions. Picture it in a hospital, delivering supplies, gracefully pausing for patients or staff, navigating busy corridors with quiet competence. Think of it in an automated inspection role, meticulously following a pre-defined route in a factory, scanning for anomalies, yet able to avoid unexpected machinery or personnel.

Artemis represents more than just a piece of engineering; it's a glimpse into a future where machines aren't just obedient, but inherently aware. It's a stepping stone towards truly intelligent automation, where the path is followed not just with precision, but with thoughtful, brainy caution, making our automated environments safer, smarter, and infinitely more capable[51-94].

II. PROBLEM STATEMENT

Inefficient navigation: Develop a control algorithm (e.g., a PID controller) that can handle sharp curves and intricate path geometries without significant deviation or oscillation.

Reactive obstacle handling: Implement a decision-making system that moves beyond a simple "stop-and-wait" or single evasive maneuver. The robot should evaluate multiple potential paths and select the most efficient route around an obstacle to return to the line quickly.

Environmental adaptability: The system must be robust enough to operate consistently under varying conditions, such as different ambient lighting, which can affect sensor performance.

Real-time performance: Ensure the integration of line-tracking sensors (e.g., IR) and obstacle detection sensors (e.g., ultrasonic) is efficient enough to enable seamless, real-time decision-making without processing delays

III. WORKING

Line Following: IR sensors detect the difference in reflectivity between the black line and the white background. Based on sensor input, the microcontroller adjusts motor speeds to keep the robot on the line.

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Obstacle Detection: The ultrasonic sensor continuously measures distance ahead. If the measured distance is below a set threshold (e.g.,15 cm), the robot stops and waits or reroutes.

The developed robot successfully demonstrated its ability to follow a designated path while intelligently avoiding obstacles. During testing, the line-following system, driven by infrared (IR) sensors, accurately detected and followed both straight and curved black lines on a white surface. The robot maintained consistent alignment with the path, with only minor adjustments needed during sharp turns, which were handled effectively by the programmed logic and motor control .

The robot was tested on a predefined black line track with various turns and obstacles placed at random intervals. The results showed:

Line Tracking Accuracy: ~95% on standard curves

Obstacle Detection Accuracy: >90% within 15 cm range

Reaction Time to Obstacle: ~ 100 ms

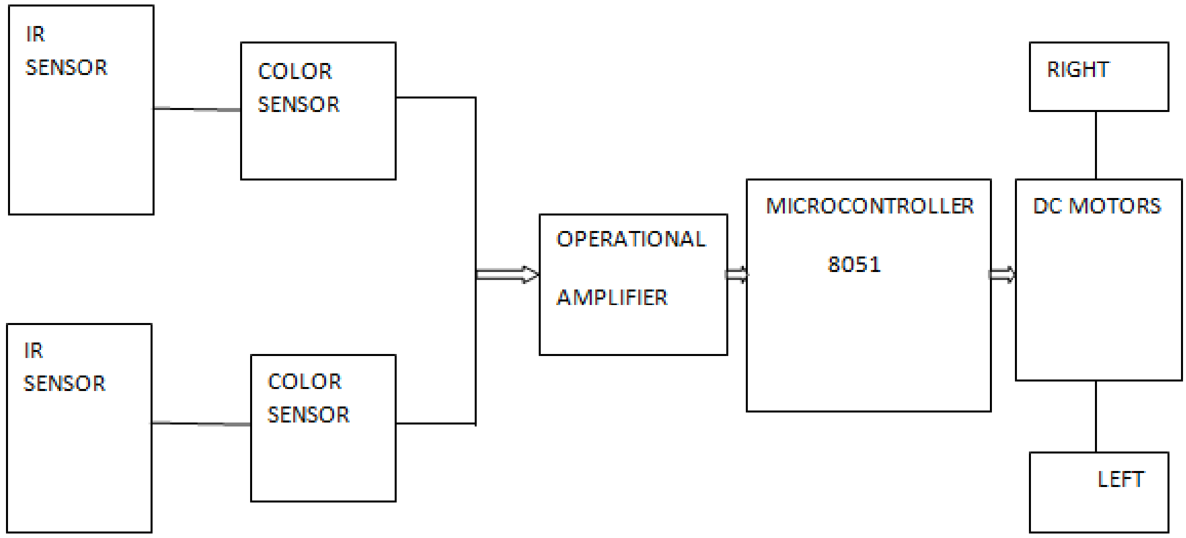

Figure 1: Block Diagram

IV. ADVANTAGE & APPLICATION

4.1 Key Advantages

Assistive Mobility: A Person With Severe Mobility Impairments Could Use Their Thoughts To Control A Line-Following Wheelchair That Also Avoids Unexpected Objects In Its Path.

Improved Human-Robot Collaboration: In Factories, A Worker Could Use Bci To Issue High-Level Commands, Such As "Deliver To Station B."

High-Level Strategic Control: In Fields Like Disaster Management, A Bci-Controlled Robot Can Be Deployed To Hazardous Areas

Enhanced Educational Tool: For Stem Education, The Project Offers A Hands-On Learning Experience That Goes Beyond Basic Robotics

4.2 Diverse Applications

Automated Guided Vehicles (Agvs) In Warehouses

Smart Transportation Systems

Educational Robotics

Line-Based Delivery Robots

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V. CONCLUSION

The proposed autonomous line-following robot with obstacle detection demonstrates reliable navigation along a path while responding effectively to obstacles. Future improvements could include adding path-planning algorithms, more advanced sensor.

The development of a line-following robot with obstacle detection demonstrates the effective integration of basic robotics and sensor technologies to achieve autonomous navigation. By combining line-tracking capabilities with real-time obstacle avoidance, the robot is able to follow a predefined path while safely responding to unexpected objects in its way. This project highlights the practical application of infrared and ultrasonic sensors, as well as microcontroller programming, in creating a responsive and intelligent robotic system. Overall, it serves as a foundational step toward more advanced autonomous robots and provides valuable insights into automation, control systems, and real-world problem-solving in robotics.

The project achieved its main goal of creating a robot that can independently follow a path while also identifying and avoiding obstacles. This shows that basic robotic systems, when equipped with the right sensors and control logic, can perform complex tasks with efficiency. It's a solid example of how automation can be applied in real-world scenarios such as warehouse navigation or delivery robots.

VI. FUTURE SCOPES

Industrial Automation : This Can Reduce The Need For Human Labor In Repetitive And Dangerous Tasks.

Smart Delivery System: It Can Navigate Indoor Environments Safely Using Advanced Sensors And Mapping Techniques.

Autonomous Vehicle Development: This Project Serves As A Foundation For Building Self-Driving Vehicles On A Smaller Scale.

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