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A Comprehensive Survey on Fault Detection in Wind Turbine Blades Using Non-Destructive Testing and Machine Learning Techniques

Rushikesh Hole, Yash Jadhav, Aniket Kadlag, Mayur Kasar, Savita Vibhute Smt. Kashibai Navale College of Engineering, Pune, Maharashtra, India

Abstract: Wind turbines play a crucial role in renewable energy generation, but their performance and longevity are significantly affected by the condition of their blades. Faults such as cracks, erosion, and other structural damage can reduce efficiency, increase maintenance costs, and potentially lead to catastrophic failures. Traditional inspection methods, often involving manual inspections and ground-based observations, can be time- consuming, costly, and occasionally dangerous. This study investigates advanced techniques for wind turbine blade fault detection by combining non-destructive testing methods and machine learning algorithms. We utilize vibration-based sensors, acoustic emissions, and thermographic imaging to capture data from the blades, which is then analyzed using signal processing techniques and convolutional neural networks (CNNs) to identify and classify potential faults

Keywords: Wind Turbine, Convolutional Neural Network, Pre-processing, Blade, Fault, Machine Learning, Deep Learning

I. INTRODUCTION

Wind power has emerged as a main renewable power supply because of its low environmental effect and capacity to satisfy international power demands. Wind mills, the number one gadgets for harnessing wind power, convert the kinetic power of the wind into electric energy. A key issue of those mills is the blade, that's continuously subjected to various environmental situations consisting of excessive wind speeds, rain, hail, and temperature fluctuations. These environmental factors, mixed with the mechanical strain of operation, result in put on and tear, in the end inflicting faults consisting of cracks, delamination, Early detection of faults in wind turbine blades is important to save you catastrophic failures, lessen operational downtime, and limit renovation costs. Traditionally, inspections have depended on guide strategies, consisting of visible inspection and periodic renovation, which can be time- consuming, labor-intensive, and regularly inadequate for detecting inner or early- degree faults.

II. RELATED WORK

The development of Wind Turbine Blade Fault Detection draws upon a rich body of research in the areas of Fault Detection, machine learning, and AI. Many existing systems have explored the use of Convolutional Neural Networks (CNNs) and other machine learning techniques for Wind Turbine Fault Detection.

A key influence on Wind Turbine Fault Detection is the work by Benjamin Collier et al., who research focuses on leveraging fusion imaging, which combines thermal and RGB data, for the inspection of Wind Turbine Blades[1] Wind Turbine Blade Fault Detection via Thermal Imaging Using Deep Learning

Another important study is by Xuefei Wang et al., who developed a Wavelet Package Energy Transmissibility Function and Its Application to Wind Turbine Blade Fault Detection. To harvest wind energy from nature, wind turbines are increasingly installed globally, and the blades are the most essential components within the turbine system. ts advantages over a number of existing methods are also demonstrated [2]

A Conditional Convolutional Autoencoder Based Method for Monitoring Wind Turbine Blade Breakages, the work by Luoxiao Yang, Zijun Zhang, a conditional convolutional autoencoder based monitoring method, which is of two-fold, for identifying wind turbine blade breakages. [3].

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The development of an New Hybrid Fault Detection Method for Wind Turbine Blades Using Recursive PCA and Wavelet-Based PDF, as proposed by Milad Rezamand et al., a new condition monitoring approach for extracting fault signatures in wind turbine blades by utilizing the data from a real-time Supervisory Control and Data Acquisition (SCADA) system. [4].

Acoustic Emission Analysis for Wind Turbine Blade Bearing Fault Detection Under Time- Varying Low-Speed and Heavy Blade Load Conditions by Zepeng Liu et al., explored a acoustic emission (AE) analysis to diagnose an industrial-scale and slow-speed wind turbineblade bearing. The main challenge for AE analysis that the fault signals are mingled with heavy noise. As a result, the objective of this article is tofilter the raw AE signals and extract weak fault signals [5].

The Wind Turbine Using Pitch Symmetrical- component Analysis by Lijun He et al., which approach turns out to be the first hardware-free (no additional hardware needed) method to remotely monitor and diagnose multi-axis wind turbine pitch bearing condition. [6].

In Automatic Discontinuity Classification of Wind-turbine Blades Using A-scan-based Convolutional Neural Network, Jiyeon Choung, that $pro \Box$ posed CNN classifier design demonstrates a classification Results of the study demonstrate that the proposed CNN classifier is capable of automatically classifying the discontinuities of WTB with high accuracy, all of which could be considered as defect candidates. [7].

Lastly, the work by H. Badihi et al. on Fault- Tolerant Individual Pitch Control for Load Mitigation in Wind Turbines with Actuator Faults. The greater structural flexibility of such machines necessitates the development of reliable load mitigation techniques to alleviate the effects of asymmetric wind loads and fatigue. [8]

Parameter	Algorithm	Limitation and Future Work
Dataset Diversity	Convolutional	Lack of standardized datasets can hinder consistency in real-world applications;
	Neural Networks	explore creating or sourcing standardized datasets for
	(CNNs)	improved accuracy.
Image Pre-	CNN-based	Sensitivity to variations in lighting and camera angles; develop advanced image
processing	classification	enhancement techniques for better adaptability.
Augmented	CNN and AR	Complex backgrounds can affect classification performance; investigate streamlined
Reality	integration	methods for AR that enhance user interaction without compromising accuracy.
Hybrid Models	CNN + RNN +	Higher computational complexity may limit real- time performance; assess
	LSTM	feasibility of integrating temporal features without significant resource costs.
Hyper	Various CNN	Requires extensive tuning for optimal performance; automate hyper parameter
parameter	architectures	tuning processes for efficiency.
Optimization		
Lightweight	CNN	Low- complexity models may sacrifice some accuracy; balance model size and
Models		accuracy specifically for mobile platforms.
Mobile	CNN for food	Limited functionality in handling both fresh and packaged foods effectively;
Application	recognition	integrate QR code scanning for comprehensive food identification.
Performance	CNN	Deeper models require more resources, affecting mobile responsiveness; evaluate
Trade-offs		lighter models that maintain a balance between accuracy and computational cost.
Real-time	CNN vs. YOLO	YOLO provides speed, but CNN offers greater accuracy; explore YOLO integration
Classification		for environments requiring rapid classification.
Mixed Reality	Mixed Reality	Current implementation does not include mixed reality for user interaction;
Integration	+ deep learning	investigate methods to incorporate mixed reality for immersive dietary information.
	models	

TABLE I. SUMMARY OF RELATED WORK/GAP ANALYSIS

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III. PROPOSED WORK

The proposed work encompasses the dataset used for wind turbine blade fault detection, the preprocessing methods, and the detailed algorithmic methodology leveraging machine learning and image processing techniques.

A. DATASET DESCRIPTION

1. Data Collection

The dataset used in this study consists of thermal and infrared images of wind turbine blades, acquired from public repositories and real-world field inspections. The images represent both healthy and faulty blade conditions, with known labels indicating the presence and type of fault (e.g., cracks, delamination, erosion). These serve as the ground truth for training machine learning models.

2. Preprocessing Steps

Before model training, preprocessing is applied to enhance image quality and ensure consistent input across samples:

• Grayscale Conversion: All images are converted to grayscale to focus on texture and structural patterns, removing irrelevant color data.

• Normalization: Pixel intensities are normalized to a range between 0 and 1 for numerical stability.

• Resizing: All images are resized (e.g., to 128×128 or 224×224 pixels) for uniformity and compatibility with CNN input dimensions.

• Noise Reduction: Gaussian or median filters are applied to suppress image noise while preserving fault edges.

• Histogram Equalization: Enhances image contrast to highlight cracks or fault lines more effectively.

• Augmentation: Techniques like rotation, flipping, scaling, and shearing are used to improve model generalization and handle variance in real-world conditions

3. Dataset Splitting

The data is split into training, validation, and testing subsets to evaluate model performance fairly:

- Training Set: ~70% of the images used to train the CNN model and learn features.
- Validation Set: ~10% used to tune hyperparameters and prevent overfitting.
- Test Set: ~20% reserved for final model evaluation on unseen data.

4. Class Distribution

The dataset includes balanced samples of multiple fault types and normal blade images. When imbalance occurs, oversampling or synthetic data generation is applied to ensure fair learning across classes.

B. PROPOSED METHODOLOGY AND ALGORITHMIC DETAIL

1. User Interface

The system is designed to be used by maintenance engineers or drone operators. Users upload images of turbine blades through a web or desktop application interface.

2. Input as Image

The primary input is a thermal or visual image of the wind turbine blade, captured via UAV drones or manual inspection devices. These images contain visible indicators of potential faults.

3. Train Dataset

The dataset of labeled blade images is used to train a Convolutional Neural Network (CNN). The model is expected to learn to differentiate between healthy and faulty blades based on patterns, textures, and anomalies visible in the image.

4. Preprocessing (Image Enhancement) Captured blade images undergo preprocessing steps, such as RGB to grayscale conversion, noise reduction, and contrast enhancement to improve feature detection.

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5. Feature Extraction

The CNN model automatically learns and extracts high-level features from the images, such as edges, texture discontinuities, and fault signatures (e.g., cracks or erosion lines).

6. Classification (CNN Algorithm)

The processed image data is fed into a CNN model, which classifies it into categories such as:

- Normal blade
- Cracked blade
- · Delaminated blade



Fig 3.1: System Architecture

Fault Detection Output

Once classified, the model displays the detected condition of the blade. A confidence score may also be shown to indicate prediction reliability.

Final Output and Action

The final output includes the predicted fault type (or healthy status). This information can be stored in a database or forwarded to a maintenance team for further inspection or repair scheduling.

IV. RESULTS AND DISCUSSIONS

The results and discussions involve the accuracy, loss noticed in the model: Confusion Matrix Analysis



Fig 4.1 Confusion Matrix

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The confusion matrix in Fig 4.1 illustrates the classification results across various blade fault classes such as "crack," "erosion," "delamination," and "healthy." A higher number of correct predictions along the diagonal indicates the model's strong performance in distinguishing faults.

Some misclassifications occur when visual or textural features of two fault types resemble each other, such as cracks being confused with erosion. These misclassifications suggest potential improvements in the preprocessing pipeline or the need for additional training data with better feature diversity.

Model Accuracy Analysis





As shown in Fig 4.2, the model's training and validation accuracy steadily improve over the course of training (e.g., across 100–200 epochs). The increasing trend indicates effective learning and feature extraction by the CNN.

Occasionally, validation accuracy surpasses training accuracy. This might be attributed to regularization or data augmentation during training, enhancing generalization. Spikes in test accuracy can also be due to varying difficulty across batches.

Overall, the upward trajectory of accuracy metrics reflects that the CNN model successfully identifies blade conditions with high reliability

Model Loss Analysis

The loss graph (Fig 4.3) presents how the training and validation loss decrease over time, confirming model convergence and optimization of its internal parameters







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A smooth and consistent decline in both training and validation loss curves without large oscillations indicates stable learning. If test loss is unusually lower than training loss, it may point to potential data leakage or the model being inadvertently exposed to validation data patterns.

The observed loss behavior confirms that the CNN effectively generalizes and fine-tunes its decision boundaries for fault classification.

ROC Curve Analysis





The ROC curve (Fig 4.4) plots the true positive rate against the false positive rate across classification thresholds. A curve bending toward the upper-left corner signifies a high-performing model.

The area under the ROC curve (AUC) being close to 1 reflects excellent sensitivity and specificity. The model is effective in distinguishing between faulty and healthy blade samples and demonstrates robustness in its prediction performance across all fault categories.

Precision-Recall Curve Analysis



The precision-recall curve (Fig 4.5) illustrates how precision and recall trade off across different thresholds. High precision with lower recall may indicate a conservative model that avoids misclassifications but may miss some subtle fault cases.

When the threshold is optimized, a balanced precision-recall trade-off is achieved. This ensures the model not only classifies high-confidence faults but also identifies more ambiguous or less visually distinct faults with reasonable accuracy. In practice, adjusting the classification threshold based on application criticality (e.g., avoiding false negatives in safety-critical turbines) can further improve model utility.

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V. CONCLUSION

Early and accurate detection of faults in wind turbine blades is essential for ensuring operational safety, minimizing maintenance costs, and improving energy efficiency. Faults such as cracks, delamination, and erosion, if undetected, can lead to serious mechanical failures and downtime. Conventional inspection techniques, though widely used, are often manual, time- consuming, and prone to human error.

This paper presents an automated fault detection system for wind turbine blades using image processing and machine learning techniques. The approach enhances blade images using filtering and normalization techniques to reduce noise and highlight fault features. A Convolutional Neural Network (CNN) is then trained to classify blade conditions based on visual patterns in the images. Compared to traditional inspection methods, this automated system offers improved accuracy, faster fault recognition, and minimal human intervention.

The system demonstrates its effectiveness by accurately detecting multiple fault types under varied conditions, suggesting its potential use in real-time monitoring and predictive maintenance frameworks.

Future work may include optimizing the algorithm for deployment on UAVs or real-time monitoring systems, improving performance with higher- resolution data, and expanding the dataset to cover a wider range of fault types and environmental conditions. Integrating deep learning techniques such as transfer learning or advanced attention- based models could further improve classification accuracy.

With modern image processing and AI-based classification, this work represents a step toward building a reliable, scalable, and efficient wind turbine blade fault detection system that can support better maintenance planning and extend the operational life of renewable energy assets.

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