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Route Optimization Solution for Courier Services

Dr. Amol Pande¹, Atul Mahajan², Vitthal kudav³, Rushikesh Manje⁴, Sangaram Lad⁵

Professor & HOD, Department of Computer Engineering¹ Student, Department of Computer Engineering^{2 3 4 5} Datta Meghe College of Engineering, Navi Mumbai, India

Abstract: Route optimization is a key component in modern-day logistics, delivery services, and transportation planning, where the primary objective is to identify the most time-efficient and resourceeffective paths between multiple destinations. The conventional approach to route optimization often relies on pre-defined or static road network data, which fails to account for the constantly changing nature of urban traffic conditions. The present work proposes a dynamic and data-driven approach for route optimization by integrating graph theory with real-time traffic data. A specific geographical area is selected and modelled as a weighted graph, where intersections or coordinates act as nodes and the roads connecting them are treated as edges. Initially, edge weights are assigned based on estimated travel times or distances. However, to enhance accuracy, these static weights are dynamically updated using live traffic data obtained from the Google Maps API. These updates reflect real-world variations such as congestion, road closures, and delays, which significantly impact the travel time along different paths. Dijkstra's algorithm, a well-established shortest path algorithm, is employed to compute the minimum time routes between any two nodes in the graph. It is particularly effective due to its ability to find optimal paths in graphs with non-negative edge weights and its relatively low computational complexity for sparse graphs. The algorithm is adapted to work with the dynamically updated weights, ensuring that every routing decision is made based on the most recent and accurate traffic conditions. The approach is further extended to support routing for multiple destinations in a single trip, commonly encountered in delivery and courier services. By iteratively applying Dijkstra's algorithm and updating travel times in real-time, the system can generate optimized multi-stop routes that minimize total delivery time and operational costs.

Keywords: Route optimization, last-mile delivery, adaptive routing, dynamic adjustments, real-time traffic data, fuel efficiency, cost reduction, optimization algorithms, travel time minimization, OR-Tools, graph-based routing, logistics efficiency, scalability, operational savings, intelligent transportation systems, delivery prioritization, sustainable logistics, data-driven decision making, smart mobility solutions

I. INTRODUCTION

In today's world of rapidly evolving logistics and transportation systems, efficient route planning has become a critical component in ensuring timely deliveries, cost savings, and optimal resource utilization. Traditional routing techniques rely heavily on static maps and predefined conditions that do not adapt well to dynamic, real-time changes such as traffic congestion, road closures, or construction work. This lack of adaptability can lead to increased delivery times, fuel consumption, and operational inefficiencies.

Dynamic Route Optimization addresses these challenges by incorporating real-time data into the route planning process. By leveraging advanced algorithms like Dijkstra's algorithm in combination with live traffic data sourced through the Google Maps API, our system intelligently adjusts routes based on current road conditions. This enables the calculation of the most efficient paths between multiple destinations, optimizing the overall delivery or travel experience.

Our approach involves modeling a particular area as a weighted graph where nodes represent locations and edges denote roads. Edge weights reflect travel times and are dynamically updated based on real-time traffic data. Using

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Dijkstra's algorithm, the shortest path between various waypoints is computed, ensuring that the selected routes reflect current traffic scenarios. Furthermore, the system supports multi-stop routing, providing optimized paths for delivery services covering multiple destinations.

The proposed solution provides a scalable and adaptable framework that can be applied across diverse sectors such as logistics, ridesharing, public transportation, and emergency services. It also enables integration with historical data to further enhance prediction accuracy and routing efficiency.

II. LITERATURE SURVEY

Existing Research:

Predictive Analytics for Last-Mile Delivery Optimization

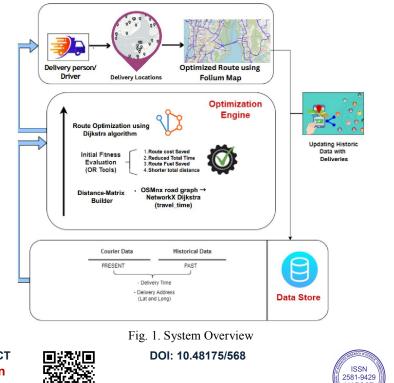
A study published in the European Journal of Logistics, Purchasing and Supply Chain Management examines the use of predictive analytics in last-mile delivery optimization. It highlights how real-time traffic data, customer preferences, and delivery constraints can be integrated into dynamic routing models to improve efficiency. The research discusses traditional Vehicle Routing Problem (VRP) models and their extensions, such as VRP with Time Windows (VRPTW) and Dynamic VRP (DVRP), and introduces machine learning techniques for better route prediction.

AI-Driven Optimization in Last-Mile Logistics

Research from *MIT* explores how artificial intelligence and machine learning technologies enhance last-mile delivery operations. The study demonstrates that AI-driven route optimization significantly reduces delivery times and fuel consumption. It also discusses neural network architectures optimized for urban delivery scenarios, showing improvements in estimated delivery windows and fleet management.

Hybrid Delivery Networks and Sustainability

A review published in MDPI focuses on hybrid delivery networks integrating drones, ground robots, and conventional vehicles. The study highlights how AI and IoT improve predictive analytics, dynamic routing, and fleet management. It also discusses sustainable logistics approaches, such as electric vehicle fleets and shared delivery infrastructures, which help minimize environmental impact.



III. PROPOSED SYSTEM

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The proposed system is designed to optimize last-mile delivery routing using graph-based mapping, heuristic optimization, and interactive visualizations. It reduces travel distance, time, fuel consumption, and costs while dynamically adjusting to real-world constraints like traffic conditions and road accessibility.

This system is only a model, developed as a proof of concept for delivery route optimization. It is not a final user product but serves as a framework for testing and validating efficiency improvements in routing strategies.

System Architecture

1. Data Collection and Preprocessing

Location data, including latitude, longitude, and addresses, is extracted from a regional dataset covering Mumbai, Navi Mumbai, and Thane.

Delivery points are filtered and structured for routing analysis. Coordinates are mapped to nearest road network nodes to ensure real-world alignment.

2. Road Network Extraction and Distance Matrix Calculation

Using OSMnx, the system fetches the road network graph and computes travel speeds and times for each road segment. A distance matrix is created using Dijkstra's shortest path algorithm, storing time-based travel costs between nodes.

3. Route Optimization Using OR-Tools

A Vehicle Routing Problem (VRP) model is constructed to determine the most efficient delivery sequence. Optimization is performed using the PATH CHEAPEST ARC method, which selects the most cost-effective travel path iteratively.

The system dynamically adjusts routes to minimize delivery time and fuel consumption.

4. Animated Route Visualization and Performance Metrics

Folium maps visualize optimized routes interactively, allowing users to inspect delivery locations and paths

IV. IMPLEMENTATION

1. Data Collection and Preprocessing

Load a CSV dataset containing latitude, longitude, city, and address information for delivery locations across Mumbai, Navi Mumbai, and Thane.

Filter locations specific to Thane (first test case) and extract essential attributes.

Assign unique IDs to each delivery point and categorize them based on color codes for visualization (red for start point, black for delivery locations).

Code Snippet:

python import pandas as pd df = pd.read_csv("/content/drive/My Drive/mumbai_navi_thane_data.csv") city = "Thane" dtf = df[df["City"] == city][["City", "Street Address", "Latitude", "Longitude"]].reset_index(drop=True) dtf = dtf.reset_index().rename(columns={"index": "id", "Latitude": "y", "Longitude": "x"}) dtf["color"] = "black" dtf.loc[0, "color"] = "red" start = dtf.iloc[0][["y", "x"]].values

2. Road Network Extraction Using OSMnx

Retrieve the road network graph for Thane using OSMnx, ensuring routing follows actual roads. Extract travel speeds and estimated travel times for each street segment.

Visualize the road network graph to confirm connectivity.

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Code Snippet:

python import osmnx as ox G = ox.graph_from_point(start, dist=10000, network_type="drive") G = ox.add_edge_speeds(G) G = ox.add_edge_travel_times(G) fig, ax = ox.plot_graph(G, bgcolor="black", node_size=5, node_color="white", figsize=(16, 8))

3. Snapping Delivery Points to Nearest Road Nodes

Find the nearest road network node for each delivery location using OSMnx.

Replace location coordinates with those of the nearest snapped node to ensure valid routing paths.

Code Snippet:

python import networkx as nx snapped_nodes = [] snapped_coords = [] for idx, row in dtf.iterrows(): nearest_node = ox.distance.nearest_nodes(G, X=row['x'], Y=row['y']) snapped_nodes.append(nearest_node) node_data = G.nodes[nearest_node] snapped_coords.append((node_data['y'], node_data['x'])) dtf['node'] = snapped_nodes dtf['y'], dtf['x'] = zip(*snapped_coords) dtf = dtf.drop_duplicates("node", keep='first')

Building the Distance Matrix Using NetworkX

Construct a distance matrix using Dijkstra's shortest path algorithm to calculate shortest travel times between delivery points.

Store results in a structured matrix, which is used for optimizing the delivery route sequence.

Code Snippet:

python

import numpy as np def f(a, b):

try:

return nx.shortest_path_length(G, source=a, target=b, method='dijkstra', weight='travel_time')

except: return np.nan

distance_matrix = np.asarray([[f(a, b) for b in dtf["node"].tolist()] for a in dtf["node"].tolist()]) distance_matrix = pd.DataFrame(distance_matrix, columns=dtf["node"].values, index=dtf["node"].values) distance_matrix = distance_matrix.fillna(distance_matrix.max().max()).round().astype(int)

5. Route Optimization Using OR-Tools

Define a Vehicle Routing Problem (VRP) model.

Use OR-Tools to apply the PATH CHEAPEST ARC algorithm, which selects the shortest travel path iteratively. Extract the optimized route sequence and compute total travel time savings.

Code Snippet:

python

from ortools.constraint_solver import pywrapcp, routing_enums_pb2

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drivers = 1lst nodes = dtf["node"].tolist() start node = dtf.iloc[0]["node"] manager = pywrapcp.RoutingIndexManager(len(lst_nodes), drivers, lst_nodes.index(start_node)) model = pywrapcp.RoutingModel(manager) def get distance(from index, to index): return distance matrix.iloc[from index, to index] distance = model.RegisterTransitCallback(get distance) model.SetArcCostEvaluatorOfAllVehicles(distance) parameters = pywrapcp.DefaultRoutingSearchParameters() parameters.first solution strategy = routing enums pb2.FirstSolutionStrategy.PATH CHEAPEST ARC solution = model.SolveWithParameters(parameters) index = model.Start(0)route idx = [] route_distance = 0 while not model.IsEnd(index): route idx.append(manager.IndexToNode(index)) previous index = index index = solution.Value(model.NextVar(index)) route distance += get distance(previous index, index) lst route = [lst nodes[i] for i in route idx] print(f'Total distance: {round(route_distance / 1000, 2)} km')

6. Visualization Using Folium and Plotly

Display optimized delivery locations on a Folium map. Animate real-time delivery tracking using Plotly.

Code Snippet:

import folium
route_map = folium.Map(location=[G.nodes[lst_route[0]]['y'], G.nodes[lst_route[0]]['x']], zoom_start=14)
folium.PolyLine([(G.nodes[n]['y'], G.nodes[n]['x']) for n in lst_route], color="blue",
weight=2.5).add_to(route_map)
route_map

7. Comparison with Unoptimized Route

Simulate greedy nearest-neighbor delivery to compare performance. Compute distance saved, time saved, fuel efficiency, and cost reduction. Code Snippet: python unvisited = set(lst_nodes) current = start_node unoptimized_route = [current] unvisited.remove(current) while unvisited: next_node = min(unvisited, key=lambda node: distance_matrix.loc[current, node]) unoptimized_route.append(next_node) unvisited.remove(next_node)

current = next_node

unoptimized_time = sum(distance_matrix.loc[a, b] for a, b in zip(unoptimized_route[:-1],

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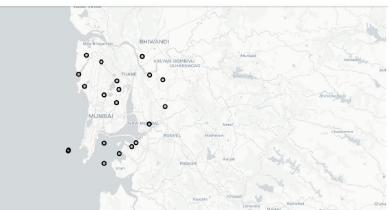
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unoptimized_route[1:]))
optimized_time = route_distance
optimized_distance_km = optimized_time / 3600 * 30
unoptimized_distance_km = unoptimized_time / 3600 * 30
fuel_saved = (unoptimized_distance_km - optimized_distance_km) / 12
cost_saved = fuel_saved * 100

8. Final Output

- Maps displaying optimized delivery routes.
- Animated tracking of package distribution.
- Performance comparisons highlighting savings in distance, time, fuel, and cost.



V. RESULTS AND DISCUSSION

Fig. 2. Delivery Locations

Map showing delivery locations marked with black dots, representing the destinations to be visited during the delivery route.



Fig. 3. Distance Graph

Visualizes the pairwise travel times between delivery nodes using a heatmap, where lighter shades indicate shorter travel times and darker shades represent longer or inaccessible paths

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Fig. 4. Optimised Route Generation

Displays the computed shortest and most efficient delivery route starting from the warehouse, covering all selected delivery points based on travel time optimization.

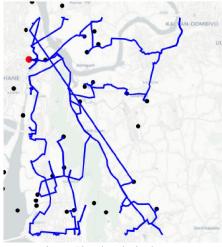


Fig. 5. Simulated Final Route

Visualizes the animated progression of the delivery vehicle along the optimized route, simulating package drop-offs at each location in real-time.

VI. FUTURE SCOPE

Integration of the Model into a Working Product: Overview of the Product

The model can be developed into a smart last-mile delivery optimization platform, used by logistics companies and e-commerce businesses. This product would serve as a real-time delivery route planner, dynamically adjusting delivery sequences based on live traffic conditions, order changes, and fleet availability.

Automated Route Optimization

The system would integrate with delivery management software, automatically computing the most efficient paths. It would use real-time traffic data to dynamically update routes and prevent delays.

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Multi-Vehicle Fleet Coordination

The product could manage multiple delivery vehicles rather than just one. The system would assign delivery tasks intelligently across available drivers based on location proximity.

Integration with GPS and Tracking Systems

It would connect to GPS devices inside delivery vehicles for real-time navigation.

Customers could track their deliveries in real time, enhancing transparency.

Mobile and Web Dashboard

A mobile app and web interface would allow fleet managers to monitor deliveries.

Drivers would receive optimized routes directly on their mobile devices.

AI-Based Demand Prediction

The system could analyse past delivery trends and predict peak demand periods. Businesses could pre-adjust routes and fleet availability based on expected order volumes.

VII. CONCLUSION

- Successful optimization ensures that delivery operations run with maximum efficiency.

- By continuously refining travel paths, deliveries are completed in less time, avoiding unnecessary delays.
- This adaptability directly leads to lower fuel consumption, as vehicles take the most efficient routes, minimizing idle time and distance travelled.
- Reduced fuel use not only cuts operational costs but also contributes to sustainability efforts by lowering emissions.
- The ability to optimize delivery routes also results in significant cost savings, as companies can achieve higher delivery
- throughput with fewer resources, maximizing efficiency and profitability.

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