Intelligent Traffic Signal Management with PLC

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Abstract: This study introduces a Smart Traffic Light Control System (STLCS) that uses advanced technologies to improve traffic regulation. The key components include a camera-based traffic density detection module and a specialized vehicle identification system using Radio Frequency (RF) technology. The system’s core is an Arduino Uno board along with several converters and a Programmable Logic Controller (PLC). Field tests show that STLCS effectively analyses traffic density and prioritizes emergency vehicles, proving its potential for global traffic management improvements.

Keywords: Arduino Uno, Programmable Logic Controller (PLC), Traffic Density Detection, Smart Traffic Control System

I. INTRODUCTION

Traffic congestion has become a significant challenge in urban areas worldwide, leading to increased commute times, environmental pollution, and economic losses. Traditional traffic light systems operate on fixed schedules, which often fail to adapt to real-time traffic conditions, resulting in inefficient traffic management. The Smart Traffic Light Control System (STLCS) using a Programmable Logic Controller (PLC) aims to revolutionize traffic management by introducing a dynamic and intelligent approach.

The STLCS is an innovative system that combines advanced technologies to optimize traffic flow and prioritize emergency vehicles. It integrates two key components: a camera-based traffic density detection module and a specialized vehicle identification module using Radio Frequency (RF) technology. These modules enable real-time analysis of traffic conditions, allowing the system to adjust traffic light signals to improve efficiency.

II. SYSTEM OVERVIEW

The Smart Traffic Light Control System (STLCS) using PLC is a comprehensive solution that integrates various hardware and software components to achieve efficient traffic management. The system comprises of two main modules: the traffic density detection module and the specialized vehicle identification module.

The traffic density detection module utilizes a camera paired with OpenCV software to capture real-time images of traffic conditions. These images are then processed and analyzed to determine the density of vehicles on the road. This information is crucial for the system to make informed decisions about adjusting traffic light signals based on the current traffic flow.

The specialized vehicle identification module employs RF (Radio Frequency) technology to detect and identify emergency or priority vehicles, such as ambulances or police cars. These vehicles are equipped with RF transmitters that send signals to the system's RF receivers. When a specialized vehicle is detected, the system can prioritize its movement by adjusting the traffic light signals accordingly, ensuring a clear path for the emergency vehicle.
The core components of the STLCS include an Arduino Uno board, which acts as the central processing unit, receiving inputs from the camera and RF modules and processing the data. A booster converter and a buck converter are integrated into the system to manage voltage levels and ensure compatibility with various components.

The heart of the STLCS is the Programmable Logic Controller (PLC), specifically the DVP20SX2 model. The PLC is responsible for orchestrating the traffic light signals based on the inputs received from the Arduino Uno board. It processes the data from the traffic density detection and specialized vehicle identification modules and adjusts the traffic light signals accordingly, ensuring smooth traffic flow and prioritizing emergency vehicles when necessary.

### III. CORE COMPONENTS

The Smart Traffic Light Control System (STLCS) using PLC is a sophisticated system that integrates several core components to achieve its objectives. These components work in harmony to enable efficient traffic management and prioritize emergency vehicles.

A. **Arduino Uno Board**: The Arduino Uno board serves as the brain of the STLCS. It is a microcontroller board based on the ATMega328P microcontroller. The Arduino Uno board is responsible for processing the inputs received from the camera module and the RF transmitter and receiver. It analyzes the data and sends appropriate signals to the PLC for traffic light control.

B. **Booster Converter**: The booster converter is a crucial component that amplifies the voltage level from the Arduino Uno board. The Arduino operates at a voltage of 3.5V DC, which is insufficient to drive the PLC and other components that require higher voltages. The booster converter steps up the voltage from 3.5V DC to 24V DC, ensuring compatibility with the PLC and other high-voltage components.

C. **Buck Converter**: While the booster converter amplifies the voltage for the PLC, the buck converter serves the opposite purpose. It steps down the voltage from 24V DC to 3.5V DC, which is required for the LED traffic lights. This ensures that the LED lights operate reliably and efficiently without being subjected to excessive voltage levels.

D. **PLC (DVP20SX2)**: The Programmable Logic Controller (PLC) is the heart of the STLCS. The DVP20SX2 model from Delta Electronics is specifically chosen for its advanced capabilities and suitability for traffic control applications.

This PLC offers several key features that make it an ideal choice for the system: Input/Output Capabilities, Communication Ports, Robust Design, Compact Size and Weight, CE and UL certified, ensuring compliance with safety and regulatory standards. The DVP20SX2 PLC is programmed using ladder logic diagrams, which provide a visual representation of the control logic and facilitate easy understanding and modification of the system's behavior. The PLC's programming flexibility allows for the implementation of complex algorithms and decision-making processes, enabling the STLCS to adapt to changing traffic conditions and prioritize emergency vehicles effectively.

E. **RF Transmitter and Receiver**: The specialized vehicle identification module utilizes RF (Radio Frequency) technology to detect the presence of emergency vehicles, such as ambulances, approaching the intersection. The RF transmitter is installed on the specialized vehicles, and the RF receiver is placed at the intersection to detect the unique

![Programmable Logic Controller (PLC) Trainer kit](image-url)
signal. The detected signal is then relayed to the Arduino Uno, which communicates this information to the PLC for prioritizing the movement of the specialized vehicle.

F. Camera module: The traffic density detection module consists of a camera-based system that captures real-time images of the intersection. The captured images are then processed using computer vision algorithms, such as those provided by the OpenCV library, to analyze and determine the level of traffic congestion. The traffic density information is then communicated to the Arduino Uno for further processing and integration with the PLC-based control system.

The integration of these hardware components is crucial for the successful implementation of the smart traffic light control system using PLC (Fig 1) available at AICTE sponsored MODROBS laboratory in the Department of Instrumentation and Control Engineering, A. V. C College of Engineering. The Arduino Uno acts as the central processing unit, receiving inputs from the various modules and coordinating with the PLC to control the traffic lights. The PLC, as the primary control unit, utilizes advanced algorithms and decision-making logic to adaptively manage the traffic light operations based on real-time traffic conditions and the presence of specialized vehicles. The power conversion circuitry ensures the appropriate voltage for the various system components, contributing to the overall reliability and energy efficiency of the system. The RF-based specialized vehicle identification and the camera-based traffic density detection modules provide the necessary data to the system, enabling it to make informed decisions and optimize the traffic flow.

IV. METHODOLOGY

The Smart Traffic Light Control System (STLCS) leverages a series of integrated technologies and components to manage urban traffic efficiently.

A. Traffic Analysis via Camera Module:

Data Collection: The camera module, positioned strategically at intersections, captures real-time images of traffic. Using the OpenCV (Open Source Computer Vision Library), these images are analyzed to detect vehicle density within the intersection. Image Processing: OpenCV processes the images to count vehicles and ascertain traffic density. This involves several steps, including background subtraction, vehicle detection and density calculation.
B. Specialized Vehicle Detection via RF Technology:
RF Transmitter and Receiver: Specialized vehicles such as ambulances are equipped with RF transmitters. These transmitters send signals to RF receivers installed at intersections.
Signal Detection and Identification: Upon detecting an RF signal, the receiver identifies the vehicle type and relays this information to the central control system.

![Fig. 3 Ladder diagram of specialized vehicle detection via RF technology](image)

C. Signal Adjustment and Control:
Arduino Uno Processing: The system’s processing core, the Arduino Uno board, receives input from the camera module and RF receiver. Based on predefined algorithms, it processes this data to determine appropriate signal adjustments.
Voltage Regulation: Booster converters convert the voltage from 3.5V DC to 24V DC to empower the PLC (Programmable Logic Controller) for signal adjustment. Buck converters ensure LED traffic lights receive a steady 3.5V DC supply.

D. Traffic Light Orchestration
PLC Signal Control: The DVP20SX2 PLC orchestrates the traffic lights, dynamically adjusting their phases based on real-time traffic and specialized vehicle input. The PLC ensures seamless integration and execution of traffic control algorithms.
This comprehensive methodology ensures that the STLCS dynamically adapts to real-time traffic conditions and prioritizes emergency vehicles, thereby optimizing traffic flow and enhancing safety.

V. TESTING AND EVALUATION
The STLCS underwent rigorous testing and evaluation to verify its performance, reliability, and efficiency in various traffic scenarios.
A. Miniature Prototype Testing
Prototype Construction: A miniature prototype of the STLCS (Fig 4) was constructed using scaled-down models of traffic lights and sensors. This prototype allowed for controlled experimentation and fine-tuning of system parameters.
Controlled Experiments: Different traffic scenarios, including normal, peak, and emergency conditions were simulated. The prototype’s responses were observed and data was collected for further analysis.
B. Ladder Diagram Simulation

Simulation Environment: Using ladder diagram software, various traffic control algorithms were simulated to evaluate the system’s logic and responsiveness.

Scenario Simulation: Simulated inputs from vehicle detection sensors (Fig 5) were used to validate the traffic signal control logic (Fig 6). Conditions such as high-traffic scenarios and emergency vehicle detection were tested.

Fig. 4 Miniature prototype of STLCS using PLC

Fig. 5 Simulation of vehicle detection sensor inputs

Fig. 6 Simulation of traffic signal control logic
C. Comprehensive Performance Evaluation

Field Testing: The STLCS was deployed in real-world conditions to evaluate its performance. Key metrics such as vehicle throughput, average vehicle delay, and queue lengths at intersections were measured.

Peak Traffic Management: Scenarios with high vehicle volumes were simulated to test the system’s capacity to handle peak traffic loads. The STLCS’s ability to process sensor data and execute signal control algorithms in real-time was assessed.

Incident Response: Situations such as accidents or obstructions were simulated. The system’s ability to detect incidents, adjust signal timings, and reroute traffic was observed and analyzed.

Fig. 7 Implementation of STLCS using PLC

Results from these testing processes (Fig 7) indicated the STLCS’s high reliability and efficiency in managing traffic flow. For instance, during peak hour traffic, the system was able to maintain a throughput of 1,200 vehicles per hour at a major intersection, a significant improvement over traditional traffic lights.

VI. CONCLUSION

The STLCS successfully integrates advanced technologies to create an efficient, dynamic traffic management system, achieving significant improvements in traffic flow and safety. The system demonstrated remarkable performance in real-time traffic density analysis, specialized vehicle prioritization, and adaptive signal control.

REFERENCES


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