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Camouflage Drone

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Abstract: This drone is a exciting example of how technology can build or create new possibilities for future. This is a camouflage drone with the ability to change its colors which will make it invisible to our naked eyes. Artificial intelligence is also used in this drone which enables it to dodge any obstacle on its own without any commands and also recognize different facial structure with the help of mini spy camera. AI drones are equipped with advanced computer vision systems using cameras and sensors to accurately perceive the surrounding environment. Drones can take over. Facial images used for biometric identification. Protecting Civilians from criminals is getting difficult every day for authorities and governments. Meaning Several steps are necessary to protect citizens from criminals. They are also criminals in crowded places. In this paper, we will cover state-of-the-art facial recognition. The drone technology are one type of robot that is becoming increasingly popular and useful.

Keywords: Color changing, live GPS tracking, drone

I. INTRODUCTION

Camouflage drones represent a significant advancement in unmanned aerial vehicle (UAV) technology, offering a novel approach to stealth and concealment in military and security operations. These sophisticated aircraft are meticulously designed to blend seamlessly into their surrounding environments, utilizing specialized coatings, materials, and visual patterns to evade detection by radar, infrared sensors, and visual surveillance systems. The concept of camouflage drones has revolutionized reconnaissance, surveillance, and intelligence-gathering missions by providing operators with a discreet means of collecting critical information in highly contested or sensitive areas. By harnessing the principles of stealth and concealment, camouflage drones offer a strategic advantage in modern warfare and security operations, allowing for covert observation and monitoring while minimizing the risk to personnel and equipment. As a result, these advanced UAVs have become indispensable assets for military forces, law enforcement agencies, and other security organizations seeking to maintain a tactical edge in complex and dynamic operational environments.

1.1 Concept

A camouflage drone is a specialized unmanned aerial vehicle (UAV) engineered to blend seamlessly into its surroundings, effectively concealing its presence from potential threats or adversaries. These drones are meticulously designed with features that mimic the visual characteristics of their operating environment, such as foliage, terrain, or urban landscapes. Utilizing advanced camouflage technologies, including specialized coatings, materials, and visual patterns, these drones can evade detection by radar, infrared sensors, and visual surveillance systems. The primary objective of camouflage drones is to conduct reconnaissance, surveillance, and intelligence-gathering missions with minimal risk of detection, enabling military forces, law enforcement agencies, and other operators to gather critical information discreetly. By leveraging the principles of stealth and concealment, camouflage drones play a vital role in modern warfare, security operations, and intelligence gathering, providing a strategic advantage in highly contested environments while minimizing the risk to personnel and equipment.

1.2 Objectives

- Make the drone visually untraceable.
- Provides soldiers with real-time coordinates of the enemy.
- Provides real-time video of enemy territory.

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- Develop the robot that can Analyze faces different.
- These robots are designed with automatic decision making and are able to make decisions like humans based on a number of factors

1.3 Literature Review

Camouflage technique is a multipurpose robot containing Bluetooth module with GPS tracking is used for its longitudinal and latitudinal location of the device or robot.

It also has accelerometer and gyroscope module which makes the robot stable while its flying which is present in Flight Controller F4

II. HARDWARE IMPLEMENTATION

2.1 Color Sensor

In this robot we are using TCS3200 color sensor which helps to detect the color and display color through Light Emitting Diode (LED) which helps the drone to camouflage itself. This TCS3200 color sensor module uses a highquality optical sensor, which can detect all colors in combination with red, green and blue. This module provides all the features of the TCS3200 in a convenient 0.1 header that is ideal for use with PCBs. Four white LEDs provide enough light for the color sensor and allow the module to be used in any ambient light.

Specification of Color Sensor (TCS3200)-

- Maximum Input Voltage 2.7V to 5.5V \Box The Output can be programmed.
- This senor can provide power down saving feature.
- It connected directly to raspberry pi model 5.
- S0~S1: Provide output frequency
- S2~S3: Inputs is provided
- OUT Pin: This Output is indirectly connected to LED strip.
- OE Pin: The Raspberry Pi input line outputs in a high impedance state for multiple device sharing.



Fig a- Shows the pin out of TCS3200

2.2 BLDC Motor

BLDC motor operates in brushless DC mode. Due to its size and efficiency. This small but powerful electric motor uses direct current as its power source. BLDCs are becoming more and more popular, and applications that use BLDCs are also becoming more popular.

Specifications of BLDC Motor

- Manufacturer REES52
- Country of Origin India
- Model number a2212 motor | 2200kv brushless motor
- Number of Memory Sticks 1

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- Item Weight 80 g
 - Item model number a2212 motor | 2200kv brushless motor
- Voltage 10 Volts The use of drones is the most effective method of identification Face to face at a certain distance. We are using the Raspberry Pi model because it is small.



Fig b - BLDC Motor

GPS Tracking

Abbreviation of global positioning system is GPS. GPS is a navigation system with space station in mid earth orbit that transmit microwave signals and help customers determine location, direction, and time GPS is used worldwide for a variety of purposes, including tracking, surveillance, and scientific research. This device enhance the performance of controller



Fig C - GPS tracker

Arduino UNO:

The Arduino Uno is a microcontroller board based on the ATmega328 (datasheet). It has 14 digital input/output pins (of which 6 can be used as PWM outputs), 6 analog inputs, a 16 MHz ceramic resonator, a USB connection, a power jack, an ICSP header, and a reset button. It contains everything needed to support the microcontroller; simply connect it to a computer with a USB cable or power it with a AC-to-DC adapter or battery to get started. The Uno differs from all preceding boards in that it does not use the FTDI USB-to-serial driver chip. Instead, it features the Atmega16U2 (Atmega8U2 up to version R2) programmed as a USB-to-serial converter.

Specifications of Arduino UNO -

- Microcontroller -ATmega328
- Operating Voltage -5V
- Input Voltage 7-12V
- Input Voltage 6-20V
- Digital I/O Pins -14 (of which 6 provide PWM output)
- Analog Input Pins -6
- DC Current per I/O Pin -40 mA

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- DC Current for 3.3V Pin -50 mA
- Flash Memory -32 KB (ATmega328) of which 0.5 KB used by bootloader
- SRAM -2 KB (ATmega328) EEPROM 1 KB (ATmega328)
- Clock Speed- 16 MHz



Fig d - Arduino UNO

Flight Controller F4

The F4 flight controller is a popular choice in the quadcopter and drone world. It is part of the Flight Controller (FC) family and is known for its powerful computing capabilities and advanced features. F4 flight controllers typically use the STM32 F4 processor, providing faster processing speeds than previous models. They support a variety of flight modes, including acrobatic, angle, and horizon modes, and often come with built-in features such as On Screen Display (OSD), black box logging, and support for multiple communication protocols such as SBUS, IBUS, and PPM. Overall, the F4 flight controller provides a reliable and versatile platform for both drone enthusiasts and professional pilots. Specifications of Flight Controller -

- Processor: STM32 F4 series processor
- Gyroscope and Accelerometer: Integrated gyro and accelerometer sensors for stable flight performance
- Input Voltage: Typically supports a wide input voltage range, such as 2S to 6S LiPo batteries
- PWM Outputs: Multiple PWM outputs for connecting to ESCs (Electronic Speed Controllers)
- UART Ports: Multiple UART ports for connecting peripherals like GPS, receivers, telemetry modules, etc.
- Integrated OSD: On-Screen Display for real-time flight data feedback
 Blackbox: Built-in Blackbox logging for recording flight data
 Supported Communication Protocols: SBUS, IBUS, PPM, etc.
- Dimensions: Typically compact and lightweight for easy integration into various drone frames Compatible with popular flight firmware such as Betaflight, Cleanflight, and others



Fig e - Flight Controller F4

RF Transmitter & Receiver

RF Transmitter-

An RF transmitter is a device that generates and sends radio frequency signals wirelessly to a receiver. It typically consists of an oscillator circuit that generates the carrier frequency, a modulation circuit to impose data onto the carrier signal, and an antenna to radiate the modulated signal into the air. RF transmitters are used in applications such as remote controls, wireless communication systems, and IoT devices.

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Specifications-

- Frequency Range: The range of frequencies over which the transmitter can operate. Common ranges include 433 MHz, 868 MHz, 2.4 GHz, etc.
- Output Power: The strength of the transmitted signal, usually measured in milliwatts (mW) or dBm (decibels relative to one milliwatt).
- Modulation Scheme: The method used to modulate the carrier signal with the information to be transmitted, such as Amplitude Modulation (AM), Frequency Modulation (FM), or Phase Modulation (PM).
- Data Rate: The maximum rate at which data can be transmitted, typically measured in bits per second (bps) or kilobits per second (kbps).
- Operating Voltage: The voltage required to power the transmitter, usually specified in volts (V) or voltage range (e.g., 3V to 5V).
- Interface: The type of interface used to connect the transmitter to a microcontroller or other control circuitry, such as Serial Peripheral Interface (SPI) or Universal Asynchronous Receiver-Transmitter (UART).
- Size and Form Factor: The physical dimensions and package type of the transmitter module.

RF Receiver

An RF receiver is a device that captures and demodulates radio frequency signals transmitted wirelessly by an RF transmitter. It typically consists of an antenna to capture the incoming RF signals, a tuner to select the desired frequency, a demodulator to extract the baseband signal, and a decoder to recover the original data. RF receivers are used in applications such as radio communication, remote controls, wireless sensors, and satellite communication. Specifications-

- Frequency Range: The range of frequencies over which the receiver can operate, matching the transmitter's frequency range.
- Sensitivity: The minimum input signal strength required for the receiver to reliably detect and demodulate the transmitted signal, usually measured in dBm or microvolts (μ V).
- Selectivity: The ability of the receiver to reject unwanted signals from other frequencies or sources, often specified as adjacent channel rejection or image rejection.
- Data Rate: The maximum rate at which data can be received and demodulated, matching the transmitter's data rate.
- Operating Voltage: The voltage required to power the receiver, usually specified in volts (V) or voltage range
- Interface: The type of interface used to connect the receiver to a microcontroller or other control circuitry, similar to transmitter interfaces.
- Size and Form Factor: The physical dimensions and package type of the receiver module.



Fig f – Transmitter & Receiver

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III. SYSTEM BLOCK DIAGRAM





IV. CONCLUSION

This project is based on color changing and artificial intelligence with it we are able to track our enemy and get live location of the robot. Camouflaging the drone with the background detects and displays the surrounding colors, increasing the uniqueness of your project. The drones produced are managed as secure private companies or

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governments, so there is no corruption ,and the drone signals can be controlled by higher authorities, so the authorities can notice differences in the signals and lead us away. Work on site

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