IJARSCT



International Journal of Advanced Research in Science, Communication and Technology (IJARSCT)

International Open-Access, Double-Blind, Peer-Reviewed, Refereed, Multidisciplinary Online Journal

Volume 3, Issue 8, April 2023

Design and Development of UAV Based Pesticide Sprayer in Agriculture Application

Mr. Gaurav Kedar¹, Mr. Amit Bahekar², Mr. Nishant Matode³, Mr. Rohan Paralikar⁴

Mr. Suraj Wagh⁵, Mr. Sanket Wankhede⁶

Students, Bachelor of Electrical Engineering Shri Sant Gajanan Maharaj College of Engineering, Shegaon, India

Abstract: Agriculture is vital to the Indian economy. Agriculture is a major source of revenue in India. Crop production rates in agriculture are determined by a variety of factors such as temperature, humidity, rain, and so on. Which are natural causes beyond the control of farmers. Agriculture is also affected by elements such as pests, disease, fertilizers, and so on, which may be controlled by properly treating crops. Pesticides could improve crop output, but they also have an impact on human health. Crop production is determined by the pesticides and fertilizers used in the fields. However, manual handling of these items poses health risks. The World Health Organization projected that over 2.5 million pesticide poisoning incidents occur each year, with the bulk occurring in nations like India. The goal of this study is to solve the problem by automating the spraying of pesticides and fertilizers in the fields. The system is made up of an aerial sprayer, which is made up of a quadcopter and a spraying mechanism. The quadcopter is controlled by radio frequency signals, and pesticide spraying is accomplished with minimal physical work and no health risks. The goal of this project is to primarily counteract the negative effects of pesticides on humans while also covering more acres of land in a short period of time.

Keywords: Fertilizers, Drone, Radio Frequency

REFERENCES

- [1]. V. S. R. P and S. R. Gorantla, "Design and Modelling of an Affordable UAV Based Pesticide Sprayer in Agriculture Applications," 2019 Fifth International Conference on Electrical Energy Systems (ICEES). IEEE, Feb. 2019. doi: 10.1109/icees.2019.8719237.
- [2]. Kedari, S., Lohagaonkar, P.,Nimbokar, M., Palve, G., &Yevale, P. Quadcopter-A SmarterWayofPesticideSpraying. ImperialJournalofInterdisciplinaryResearch, Vol.2, No.6, 2016.
- [3]. D. Yallappa, M. Veerangouda, D. Maski, V. Palled, and M. Bheemanna, "Development and evaluation of drone mounted sprayer for pesticide applications to crops," 2017 IEEE Global Humanitarian Technology Conference (GHTC). IEEE, Oct. 2017. doi: 10.1109/ghtc.2017.8239330.
- [4]. Maddikunta, P. K. R., Hakak, S., Alazab, M., Bhattacharya, S., Gadekallu, T. R., Khan, W. Z., & Pham, Q. V. (2021). Unmanned Aerial Vehicles in Smart Agriculture: Applications, Requirements, and Challenges. IEEE Sensors Journal, 21(16), 17608 17619. https://doi.org/10.1109/JSEN.2021.3049471
- [5]. K. Anand and G. R., "An Autonomous UAV for Pesticide Spraying," International Journal of Trend in Scientific Research and Development, vol. Volume-3, no.Issue-3. South Asia Management Association, pp. 986–990, Apr. 30, 2019. doi: 10.31142/ijtsrd23161.
- [6]. S. Ahmed, H. Xin, M. Faheem, and B. Qiu, "Stability Analysis of a Sprayer UAV with a Liquid Tank with Different Outer Shapes and Inner Structures," Agriculture, vol. 12, no. 3. MDPI AG, p. 379, Mar. 08, 2022. doi: 10.3390/agriculture12030379.
- [7]. P. K. Reddy Maddikunta et al., "Unmanned Aerial Vehicles in Smart Agriculture: Applications, Requirements, and Challenges," IEEE Sensors Journal, vol. 21, no. 16. Institute of Electrical and Electronics Engineers (IEEE), pp. 17608–17619, Aug. 15, 2021. doi: 10.1109/jsen.2021.3049471.

Copyright to IJARSCT www.ijarsct.co.in DOI: 10.48175/IJARSCT-9535



16

IJARSCT



International Journal of Advanced Research in Science, Communication and Technology (IJARSCT)

International Open-Access, Double-Blind, Peer-Reviewed, Refereed, Multidisciplinary Online Journal

Volume 3, Issue 8, April 2023

- [8]. Swapnil R. Kurkute, AishwaryaThenge, Shivani Hirve, DikshaGosavi, "Cattle Health Monitoring System A Review", International Journal of Advanced Research in Computer and Communication Engineering, ISSN (Online) 2278-1021, Vol. 7, Issue 1, PP-139-140, DOI 10.17148/IJARCCE.2018.7122 January 2018.
- [9]. Karan Kumar Shaw and Vimalkumar. R, "Design and Development of a Drone for Spraying Pesticides, Fertilizers and Disinfectants," International Journal of Engineering Research and, vol. V9, no. 05. ESRSA Publications Pvt. Ltd., Jun. 02, 2020. doi: 10.17577/ijertv9is050787.
- [10]. U. R. Mogili and B. B. V. L. Deepak, "Review on Application of Drone Systems in Precision Agriculture," Procedia Computer Science, vol. 133. Elsevier BV, pp. 502–509, 2018. doi: 10.1016/j.procs.2018.07.063.
- [11]. Altug E, Ostrowski J P, Taylor C J. Quadrotor Control using Dual Camera Visual Feedback. IEEE International Conference on Robotics and Automation, Taipei, Taiwan.2003; 4294–4299p.
- [12]. Parth N Patel, Malav A Patel, Rahul M Faldu et al. Quadcopter for agricultural surveillance. Journal of Advance in Electronic and Electric Engineering. 2013; 3(4): 427–432 p.
- [13]. B. Dai, Y. He, F. Gu, L. Yang, J. Han and W. Xu, "A vision-based autonomous aerial spray system for precision agriculture," 2017 IEEE International Conference on Robotics and Biomimetics (ROBIO), Macau, 2017, pp. 507-513.

