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Smart Patient Monitoring Wireless Robot

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Abstract: *This paper report the methods for analysing, designing, improving and controlling the health care management system. Smart Robots can perform and wish for tasks in any type of environment without the continuous instruction of human. A line assistant robot is automated device programmed to follow a specific path. A line following robot carries the medicine to the patient whenever they need it based on the predefined path that can be either visible on a black line on a white surface or vice-versa. An IR sensor remote is used by the sister or electrician, based on which the data is sent to the system or the robot. In this algorithm Firebird V microcontrollers are used to deliver the requested provisions by the patients in the hospital. It uses three levels of feedback for path alignment, rotation offset and for avoiding obstacles. Since the path of the wards remains same in the hospitals, so a fixed path is defined and is loaded to the Firebird V through codes. In this project the robot used is Firebird V ATMEGA 2560.*

Keywords: Line follower robot, Firebird V ATMEGA 2560 Microcontroller, Autonomous Intelligent Robots

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