

EMG Controlled Bionic Arm

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Abstract: *Advanced prosthetic hand development faces the challenge of replicating the human hand's complexity, particularly in achieving intuitive, multi-degree-of-freedom control via EMG signals. To address this, a novel approach focuses on leveraging the deterministic structure of initial muscle contractions, using feature extraction and artificial neural networks for enhanced pattern classification. This method aims to increase controllable functions without added user effort. Simultaneously, improvements in energy efficiency, weight reduction, and miniaturization are pursued through low-power microcontrollers, optimized motor control, lightweight materials, and efficient power supplies. The overarching goal is to create prosthetic hands that offer increased functionality, reduced user burden, and a more natural control experience, bridging the gap between current technology and the capabilities of the biological hand.*

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