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Automatic Wheel Chair

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Abstract: *The main purpose of this paper presenting our revolutionary creation: A wheelchair can be driven using acceleration sensor and head movements with the possibility of avoiding obstacles. Our project Automatic wheelchair basically works on the principle of acceleration, one acceleration sensor, provides two axis, acceleration sensors whose output varies according to acceleration applied to it, by applying simple formula we calculate the amount of tilt & output of tilt will decide to move in which direction. On chair rain sensors will be installed. The rain sensor module is an easy tool for rain detection. It can be used as a switch when raindrop falls through the raining board and also for measuring rainfall intensity. We are trying to build a controlled wheelchair; the system will understand and obeys natural language motion commands such as "Take a right." Various technologies are used for developing such a system.*

Keywords: revolutionary, wheelchair, rain sensor, direction and move, temperature sensor

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