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Self Driving Load Carrier

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Abstract: *This project introduces an "Automatic remote control material handling trolley robot" is to developed by to carry any book's and parcel in collage library or other places from one to another place easily no damage to the parcels and materials. The robot is basically works on the principle of line follower robot and relay logic system. The robot is to be control the motor rotation via remote control. Firstly we press number button of remote control the relay will be RF based remote control circuit operated .The circuit are classified as one transmitter and receiver, in transmitter circuit 1to 8number of remote control are used to transmit particular signal through wireless, then operate receiver side receive signal and operate particular relay in receiver. In receiver circuit relay provide supply line follower or obstacle circuit are fitted to robot body and can be driven any of four directions like left, right, forward, back. and the robot trace black line on ground surface and also detect obstacle in front direction thane after robot stop and give the alarm. This robot will be installed in collage library for books are traveling one place to another easily and robot also applicable for the industry, shopping mall to travel small weight up to 25kg*

Keywords: Automatic remote control material handling trolley robot

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