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Ferromagnetic Pipe Climbing Robot

Mr. S. K. Chaudhary[1], Om Shashikant Gunjal[2], Yash Rajendra Naikwadi[3], Arthesh Rajendra Todker[4]
Assistant Professor, Department of Electronics Engineering[1]
B.E. Students, Department of Electronics Engineering[2,3,4]
Amrutvahini College of Engineering, Sangamner, Maharashtra, India
suman.choudhary@avcoe.org, omgunjal5010@gmail.com, yash.naikwadi2002@gmail.com, todkararthesh@gmail.com

Abstract: *Ferromagnetic pipe climbing robots have emerged as indispensable tools in various industries, offering unparalleled capabilities in infrastructure inspection and maintenance. This research paper presents a comprehensive overview of the design, development, and applications of ferromagnetic pipe climbing robots, with a keen focus on practical implementation and analytical analysis. These robots, equipped with advanced technologies and components such as Raspberry Pi-based control systems, Li-ion battery power sources, DC motors, magnetic adhesion systems, cameras, and sensor integration, revolutionize the way infrastructure is inspected and maintained. By leveraging the inherent properties of ferromagnetic materials and magnetic adhesion systems, these robots can traverse vertical and horizontal pipes with ease, reaching areas that are otherwise inaccessible or hazardous to human workers. The paper delves into the intricacies of system development, discussing in detail the functionalities and integration of key components to ensure optimal performance and reliability. Furthermore, it explores the challenges and limitations encountered in both practical and analytical analyses, shedding light on discrepancies arising from measurement inaccuracies, component tolerances, and sensor resolutions. Through a comparison of theoretical predictions with real-world testing results, the paper seeks to provide valuable insights into the performance, capabilities, and potential of ferromagnetic pipe climbing robots. Additionally, the research paper investigates the diverse applications of these robots across industries such as oil and gas, infrastructure maintenance, energy, and chemical plants, showcasing their versatility and effectiveness in addressing various inspection and maintenance needs. Case studies and examples of real-world deployments underscore the impact and significance of ferromagnetic pipe climbing robots in enhancing efficiency, safety, and productivity in industrial operations. Looking ahead, the paper identifies future prospects and emerging trends in robotics for infrastructure inspection and maintenance, highlighting opportunities for further advancements and innovation in this rapidly evolving field. Through its comprehensive analysis and insights, this research paper serves as a valuable resource for researchers, engineers, and practitioners interested in the design, development, and deployment of ferromagnetic pipe climbing robots.*

Keywords: Ferromagnetic pipe climbing robots, Robotics, Raspberry Pi

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